



"Rock-physics - From microstructure to seismic signatures"

Integrating facies-based Bayesian inversion and supervised machine learning for petrofacies characterisation in the Snadd Formation of the Goliat Field, SW Barents Sea.

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Integrating facies-based Bayesian inversion and supervised machine learning for petrofacies characterisation in the Snadd Formation of the Goliat Field, SW Barents Sea.

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ABSTRACT

Seismic petrofacies characterisation in low net-to-gross reservoirs with poor reservoir properties such as the Snadd Formation in the Goliat field, requires a multidisciplinary approach. This is especially important when the elastic properties of the desired petrofacies significantly overlap. Pore fluid corrected end-member sand and shale depth trends have been used to generate stochastic forward models for different lithology and fluid combinations in order to assess the degree of separation of different petrofacies. Subsequently, a spectral decomposition and blending of selected frequency volumes reveal some seismic fluvial geomorphological features. We then jointly inverted for impedance and facies within a Bayesian framework using facies-dependent rock physics depth trends as input. The results from the inversion are then integrated into a supervised machine learning neural network for effective porosity discrimination. Probability density functions derived from stochastic forward modelling of end-member depth trends show a decreasing seismic fluid discrimination with depth. Spectral decomposition and blending of selected frequencies reveal a dominant NNE trend compared to the regional SE – NW progradational trend, and a local E-W trend potentially related to fault activity at branches of the Troms-Finnmark Fault Complex. The facies-based inversion captures the main reservoir facies within the limits of the seismic bandwidth. Meanwhile the effective porosity predictions from the multilayer feedforward neural network are consistent with the inverted facies model, and can be

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3 used to qualitatively highlight the cleanest regions within the inverted facies model. A combination
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5 of facies-based inversion and neural network improves the seismic reservoir delineation of the
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7 Snadd Formation in the Goliat Field.
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14 Keywords: Inversion, rock physics, facies, reservoir characterisation, neural network
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20 **INTRODUCTION**

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23 The Norwegian Barents Shelf (NBS) is a frontier hydrocarbon exploration province when
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25 compared to the other parts of the Norwegian Continental Shelf (NCS) such as North Sea and
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27 Norwegian Sea. The NBS has a far more complex burial history, with differential amounts of uplift
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29 and erosion within the different basins, platform areas and local highs. Uplift and erosion introduce
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31 additional challenges and uncertainties when evaluating the petroleum system with respect to cap
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33 rock integrity, source rock maturation, and overconsolidation of the target reservoirs with respect
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35 to the present day depths. Understanding and constraining rock physics depth trends is crucial in
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37 areas with such a complex burial history.
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43 The Goliat Field is located about 85 km southeast of the Snøhvit gas field (Figure 1) in the
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45 Norwegian sector of the Barents Sea. It is the first oil field in the Norwegian sector of the Barents
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47 Sea to be in production (March 2016). The majority of the NBS discoveries indicate a dominance
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49 of gas over oil. The oil reserves in the Snadd Formation of the Goliat field were not included in
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51 the Plan for Development and Operations (PDO). As a result, the Snadd Formation has not been
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53 the focus in earlier studies from a quantitative seismic petrofacies characterisation perspective.
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3 However, a better understanding and delineation of the fluvial sand facies at the top of the Snadd
4 Formation should provide additional insight into the porosity distribution for the cleanest sand
5 intervals.
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10 From a geophysical perspective, the Snadd Formation is challenging for the seismic lithology and
11 fluid characterisation for three main reasons; i) relatively thin, silty-shaly sandstone units not ideal
12 for AVA (Amplitude Versus Angle) analysis, ii) significant petrofacies overlap in rock physics
13 elastic properties, and iii) overconsolidated reservoir due to uplift stiffens both the rock frame and
14 pore space, thereby reducing the seismic fluid sensitivity. The main objective of this study is to
15 discriminate and map out clean reservoir sands within the Snadd Formation using a
16 multidisciplinary workflow combining spectral analysis, facies-based Bayesian inversion and
17 supervised neural networks.
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33 **GEOLOGICAL SETTING**

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36 The Uralian mountain chain is one of the last collision elements close to the study area in Permian-
37 Triassic times and represents an important source area for the dominantly siliciclastic sediments.
38 Collapse and erosion of this orogeny, together with sediments from the basement rocks in the Kola
39 peninsula, gradually filled the Barents Sea area mainly from the southeast (Mørk 1999; Glørstad-
40 Clark et al., 2010; Henriksen et al., 2011b).

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43 Structurally, the Troms-Finnmark Fault Complex (TFFC) is one of several regional faults in the
44 area (Figure 1) and it cuts across the Goliat Field. The TFFC has a series of listric normal faults
45 (Faleide et al., 1984; Gabrielsen, 1984; Gabrielsen et al., 1990; Mulrooney et al., 2017) forming a
46 prominent roll-over anticline which provides structural closure for the field. Later Cenozoic uplift
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3 and exhumation in the Goliat area resulted in approximately 1000 to 1500 m of net erosion (Ohm
4 et al., 2008; Henriksen et al., 2011b; Baig et al., 2016). This implies that the reservoirs have been
5 exposed to much higher pressures and temperatures (i.e., more mechanical and chemical
6 compaction) than at their present depths.
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13 As mentioned earlier, the Snadd Formation is the main focus in this study (Figure 2a). The Barents
14 Sea was part of a large and shallow inland sea, during the time when the Snadd Formation was
15 deposited in the Late Ladinian to Early Norian (Dalland et al., 1988). According to Glørstad-Clark
16 et al. (2010), the main depocenter during this time was located around present day Loppa High.
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23 The regional sequence stratigraphic framework for the Snadd Formations has been documented by
24 several authors (Glørstad-Clark et al., 2010; Klausen et al., 2015). The chronostratigraphic
25 subdivision of the Snadd Formation is based on regionally correlated maximum flooding surfaces
26 (MFS). The Top Snadd Formation sands in the Goliat field are capped by shales of the Fruholmen
27 Formation. It represents the boundary between the Late Triassic Carnian and Norian Stages. This
28 capping shale unit shows a characteristic higher acoustic impedance (AI) than the underlying
29 Snadd Formation sands (Figure 2b). This results to a strong negative reflection coefficient. Note
30 that positive amplitudes represent negative reflection coefficients in Figure 2b due to the reverse
31 polarity of the data. The upper part of the Snadd Formation contains thicker and cleaner sands, as
32 opposed to the middle section with more heterolithic or thin interbedded (“ratty”) sands and shales.
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The base of the Snadd Formation (Ladinian) overlying the Kobbe Formation is dominated by
marine shales. This gross vertical change in the sand proportion can easily be seen by looking at
the gamma ray log and sand flag (Figure 2b). The Snadd Formation has a southeast to northwest
regional depositional dip (Riis et al., 2008; Glørstad-Clark et al., 2010; Klausen et al., 2015). The
boundary between the Snadd Formation and the Kobbe Formation (Anisian to Early Ladinian)

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3 below, is characterized by a drop in AI from the basal anoxic shales of the Snadd Formation to the
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5 sand prone Kobbe Formation.
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9 The systematic change in the depositional environments for the Snadd Formation, from open
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11 marine at the base to non-marine fluvial sediments at the top, translates into an increase in the net-
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13 to-gross (NTG) and quality of the reservoir sands towards the top of the formation. A north – south
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15 correlation profile through the available wells is shown in Figure 3a. The wells tops are flattened
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17 at the top Snadd Formation pick. Small-scale internal flooding surfaces can be seen bounding a
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19 series of stacked fining upward channel sands (blue arrows in the zoomed view in Figure 3a) based
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21 on the gamma ray log motif. The NTG at one of the deviated wells (Well-D) shows an anomalous
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23 proportion of sand within the Snadd Formation. The same outlier well is located structurally lower
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25 in a down – faulted segment compared to the other wells and is bounded by a relay-ramp fault
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27 system (Figure 3b).
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35 **DATABASE AND METHOD**

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38 Long-offset multi-azimuth (MAZ) 3D seismic, wireline logs, prestack depth-migrated (PSDM)
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40 velocities, and stratigraphic horizons were provided by the PL229 licence. The MAZ (127°, 67°,
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42 and 7°N) 3D seismic data over the Goliat Field each covers an area of approximately 209 km².
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44 During the processing of the seismic data (Buia et al., 2010), the partial angle stacks from the
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46 individual azimuths were rotated and referenced to 127°N (consistent with previous older survey
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48 azimuth). The near-angle (17°), mid-angle (32°), and far-angle (45°) partial stacks from each
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50 rotated azimuth are stacked to provide high quality angle stacks used as input in this study.
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3 The well database consists of seven exploration and appraisal wells. Of these seven wells, two are
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5 not drilled through the entire Snadd Formation. Two of the remaining wells (oil- and brine-filled
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7 within the Snadd Formation) have been drilled through the entire formation, and in addition
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9 contain measured V_s logs. The relevant elastic logs of compressional velocity (V_p), shear velocity
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11 (V_s) and bulk density (ρ), alongside a suite of other formation evaluation logs (gamma ray,
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13 resistivity, porosity, etc.) have been used for petrofacies characterisation and discrimination during
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15 the feasibility analysis. A summary of the data-driven multidisciplinary method used to delineate
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17 clean sand units in the Snadd Formation is shown in Figure 4. The workflow can be subdivided
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19 into the following main steps:
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24 1. End member depth trend analysis and stochastic forward modelling,
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26 2. Rock physics feasibility and facies discrimination
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28 3. Well –to – seismic ties and spectral decomposition for seismic geomorphology
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30 4. Facies-based Bayesian inversion to predict absolute elastic properties and facies.
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32 5. Supervised neural network for porosity estimation
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40 **End-member depth trends and stochastic forward modelling**

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43 A rock physics feasibility analysis is important in identifying the appropriate quantitative
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45 interpretation strategy for the different gross depositional environments within a given basin. This
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47 can be done using crossplots between various well log elastic properties and geological variables
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49 like porosity, volume of shale, and water saturation. The degree of facies separation in different
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51 elastic domains as a function of depth, provides clues as to which elastic parameters best
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53 discriminate the facies of interest. Siliciclastic sediments dominate the Triassic Snadd Formation.
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3 As a result, end member sand and shale facies (Figure 5) have been picked in all the available
4 wells spanning drilled depth. These end-member picks represent the cleanest example of a specific
5 lithofacies. These picks are based on drilling reports, and the full suite of measured and computed
6 petrophysical logs. For the clean sand end-member, the variation in pore fluid properties are also
7 taken into account. The Backus average for each picked zone in the well is used as a single point
8 in the end-member depth trend. During the manual picking process, the relative quality of each
9 end-member pick is assessed from how close the individual pick histogram is to a normal
10 distribution. This ensures that small unusual outliers are not considered and leads to more robust
11 and representative end-member trends.
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24 Once the representative depth trends are obtained for the in situ fluids, Gassmann (1951) fluid
25 substitution is then applied (i.e., referencing all the fluid trends to brine) to effectively remove the
26 scatter in the elastic property depth trends due to variations in the fluid type. The quartz grain and
27 pore fluid properties used for fluid substituting the sand end-member trends are shown in Table 1.
28
29 The effective porosity and saturation for each zone pick is obtained from the well logs. The dry
30 rock bulk modulus is inverted for (using Gassmann's equation), given the moduli of quartz and
31 porosity. As a result of a varying porosity input, the inverted dry rock bulk modulus also varies as
32 a function of depth. The final brine-filled, end-member depth-dependent trends can then be used
33 as input to construct i) depth varying stochastic Amplitude Versus Angle (AVA) forward models,
34 ii) depth dependent Gaussian Probability Density Functions (PDFs) of the absolute elastic
35 properties, and iii) the effective Extended Elastic Impedance (EEI) rotation angles (Whitcombe et
36 al., 2002) for lithology and fluid stacks at different depths of investigation.
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53 The stochastic forward models (Figure 6) are based on random sampling from the PDFs at the
54 target depth, between a specified lithology and fluid composite (litho-fluid) across an interface.
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3 This stochastic forward modelling analysis goes beyond the end-member brine trends, but can also
4 include desired or expected litho-fluid composites at different depths. These trends are important
5 in understanding the key elastic parameters controlling the facies discrimination as a function of
6 depth. The depth varying PDFs can later be used to classify the inverted volumes, or other prestack
7 data cross plot combinations (i.e., AVA intercept and gradient, near- versus far-angle stacks), to
8 the desired facies of interest.
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12 These end-member depth trends may be utilised directly in building the very important low-
13 frequency model (LFM) required to obtain absolute elastic properties from a model-based
14 inversion. This requires good prior knowledge of the NTG, which is then used to specify the
15 representative proportions of the end-member trends within each stratigraphic interval. The
16 challenge in doing so is that the NTG distribution within the Snadd Formation is the main objective
17 of the study and the reason for inverting in the first place. As a result, we adopt a different approach
18 to obtain the required low-frequency model, which is explained in the facies-based simultaneous
19 inversion section of the workflow. Prior to the facies-aware inversion, we need to define the target
20 petrofacies from available well data and assign depth dependent rock physics trends.
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39 **Petrofacies classification and per-facies depth trend analysis**

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42 Rock physics crossplots such as AI versus V_p/V_s ratio, colour coded with shale volume and
43 porosity (Figure 7a and Figure 7b respectively), have the potential to reveal facies clusters or trends
44 in petroelastic space. Deciding on the number of petrofacies to invert for is not always trivial.
45 There is a trade-off between the number of different petrofacies needed for subsurface
46 characterisation and the resolution limitations (i.e., narrow bandwidth compared to well log data)
47 of the seismic.
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3 A binary petrofacies log has been created using effective porosity (PHIE) cut-off (PHIE < 12%
4 represent non-reservoir) to distinguish reservoir from non-reservoir. This cut-off is based on how
5 well the derived facies classes separate in the elastic domain. The corresponding AI versus V_p/V_s
6 PDFs of the binary facies are shown in Figure 7b. This binary log was subsequently upscaled based
7 on filtering the PHIE log using a Gaussian function over a 15-m window, and subsequently
8 applying the same cut-off. The upscaled log is used at a later stage for comparison to the inversion-
9 derived facies log at the well locations. Meanwhile, the unscaled facies log is used to define per
10 facies rock physics depth trends. Figure 8a shows the depth trends (using only five vertical wells)
11 for reservoir sand and non-reservoir facies within the Snadd and Kobbe formations interval. Two
12 deviated wells were left out of the depth trend analysis. One of these wells is used as a quality
13 control (QC) blind well for the inversion and neural network predictions. The depth trend analysis
14 provides, i) the prior facies proportions for subsequent facies-based Bayesian inversion, ii)
15 uncertainty distribution (dotted line in Figure 8a) in the elastic properties per facies with depth,
16 and iii), per-facies rock physics cross correlations (Figure 8b) between V_p , V_s , and ρ . The prior
17 probabilities obtained from the depth trends are used as initial estimates only and are adjusted
18 down slightly to account for bias in well placement (since available wells target areas with
19 expected high NTG). The uncertainty distribution of the elastic properties with depth and the
20 corresponding cross correlations provide important facies-dependent constraints during the
21 Bayesian facies-aware simultaneous inversion process.

22 **Well-to-seismic ties and spectral analysis**

23 Well ties represent a crucial step in understanding the relationship between the seismic amplitudes
24 and the impedance contrasts at the wells. This requires a comparison between a synthetic seismic
25 trace and the seismic trace at the well location. The convolutional forward model needed to create
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3 the synthetic trace requires a wavelet. This wavelet can either be derived statistically without using
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5 the wells (assuming the seismic data is zero phase), or using a deterministic approach using wells
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7 (no assumption of the phase of the data). For this work, we have used the White (1980) method to
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9 estimate the wavelets shown in Figure 9a. This deterministic method provides the appropriate
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11 wavelet scaler required to link the reflection coefficients computed at the wells to the
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13 corresponding observed seismic amplitude. The elastic logs (V_p , V_s , and Rho) are Backus averaged
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15 to the seismic bandwidth prior to convolving with the derived wavelet. The quality of the tie is
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17 quantitatively assessed using attributes such as the Proportion of Energy Predicted (PEP) and the
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19 cross correlation coefficient. The Root Mean Square (RMS) error of the wavelet obtained for each
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21 angle stack is used during the inversion to weight the contribution of the near-, mid-, and far-angle
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23 stacks differently. The signal-to-noise (SNR) at the target is estimated from the PEP following,
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$$SNR = \sqrt{\frac{PEP}{1-PEP}} \quad (1)$$

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34 A spectral decomposition is then carried out on the full stack data. This decomposes the seismic
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36 traces to user defined constituent frequencies through a Fourier transform operation within the
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38 target window for the Snadd Formation. Analysis of the resulting amplitude spectrum (Figure 9b)
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40 and the frequency cube over sand rich intervals around the wells provide insight into which
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42 frequencies to select for a Red – Green – Blue (RGB) frequency blend. Seismic geomorphologic
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44 features of interest are subsequently highlighted based on an RGB flattened horizon slice for the
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46 top Snadd Formation.
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50 **Facies-based simultaneous Bayesian inversion**

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3 Seismic data is well known to be bandlimited. However, the low-frequency component of the
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5 seismic data is more crucial to the successful application of absolute seismic inversion schemes
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7 (Cooke and Schneider, 1983). These low frequencies contain the subtle compaction trends, which,
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9 if not properly captured, will result in erroneous estimates of the absolute elastic properties,
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11 irrespective of the optimisation inversion algorithm used.
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15 Several practitioners over the years have used different methods to obtain this crucial low-
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17 frequency component of the earth. One method is to apply a high-cut frequency to horizon guided
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19 interpolations of well log elastic properties. The quality of the LFM is dependent on the number
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21 and spacing of the wells. Other methods use seismic velocities (stacking or PSDM velocities),
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23 either as a standalone input, or co-krigged with the well logs (Yenwongfai et al., 2017a). The
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25 seismic Rho and Vs LFMs can be subsequently obtained by applying rock physics transforms such
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27 as the Gardner et al. (1974) and Castagna et al. (1998) equations, respectively. The pitfall in using
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29 seismic velocities alone is that the corresponding LFMs for Vs and Rho do not contain any
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31 independent information. Therefore, in geologic scenarios where the primary facies discriminating
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33 parameter is V_p/V_s ratio, the inversion for the purpose of facies discrimination is compromised
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35 before one begins. Another method could be to use facies dependent end-member trends as input.
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37 The challenge here, as mentioned earlier, is in specifying the correct proportion of the end
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39 members, for each zone of interest, to obtain one average LFM. However, it is beyond the scope
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41 of this paper to discuss the pitfalls in constructing the LFM or a review of different inversion
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43 methods. We refer the reader to Sams and Carter (2017) for more details and alternative methods
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45 for constructing a LFM. In addition to the challenges in constructing a LFM, classical inversion
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47 algorithms treat the problem as only continuous (impedances), and ignoring facies (discrete) which
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49 together drive the seismic response.
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3 In order to overcome these limitations, Kemper and Gunning (2014) introduced a novel approach
4 where the impedances and facies are jointly inverted for in a Bayesian framework. The same
5 method was applied in this study. Here, the LFM is an output (constructed during the inversion)
6 and not an input. Facies-dependent depth trends for V_p , V_s , and ρ are used to construct two LFM
7 representatives for reservoir sand and non-reservoir facies in the Snadd Formation. This ensures
8 that the compaction trends and the associated uncertainty with depth is accounted for per facies.
9 For a detailed review on the inversion scheme, we refer the reader to Kemper and Gunning (2014).

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20 Once facies are obtained, inverse rock physics models per facies (Johansen et al., 2013) can be
21 applied to the inverted facies result to obtain petrophysical parameters like shale volume (V_{sh}),
22 PHIE, and water saturation. For good results, core data calibration is often required. In the absence
23 of available core data, multi-attribute analysis and neural networks were used to combine all
24 available data into one analysis and search for non-linear trends in the data.

31 32 **Supervised neural network**

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Neural networks have the advantage of exploiting complex non-linear relationships between
multiple input parameters to predict a target output. Step-wise linear regression based algorithms
might miss some important non-linear information vital for reservoir properties such as PHIE.
Utilising neural networks or multi-attribute seismic analysis for lithology characterisation is not
new (e.g., Hampson et al., 2001; Pramanik et al., 2004). However, there has been an increasing
trend in integrating seismic inversion products with machine learning algorithms to squeeze out
more subsurface information.

The main objective of the supervised neural network in this study is to put together in one analysis
all relevant attributes derived from the inversion which are indirectly related to the pore volume.

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3 A three-layer feedforward network has been used with a total of 15 nodes in the hidden layer. A
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5 sigmoid activation function has been used. The training process is done in time and requires a
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7 seismic consistent sampling rate (4 ms in our case) for the target porosity logs (computed from
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9 logs measured in depth). Good seismic-to-well ties are crucial during the training phase. First,
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11 single attributes are compared and ranked based on their correlation with the PHIE log at the
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13 training wells. Then, several multi-attribute combinations are compared and ranked according to
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15 the training and validation errors. The optimum number of attributes are chosen based on the
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17 validation error profile associated with the successive addition of attributes to the training process.
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19 This step tries to reduce the risk of over classifying the attributes in the final neural network. This
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21 optimum attribute set is then used as input to the multi-layer feed-forward neural network (MLFN).
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24 Optimisation of the cost function is achieved through a combination of conjugate gradient and
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26 simultaneous annealing algorithms to search for the global minimum. Meanwhile the optimum
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28 synaptic weights between the nodes are derived during the training, by backpropagation of the
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30 error in the predicted log when compared to the actual porosity log. The final extracted clean sand
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32 geobodies are based on PHIEs > 15 % within the reservoir sand predictions obtained from the
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34 facies-based inversion.
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44 **RESULTS AND DISCUSSION**

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47 Figure 5 shows Gassmann corrected end-member depth trends for sand and shale. All the trends
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49 are referenced to brine and plotted from the mudline. The dotted lines represent two standard
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51 deviations from the mean trend (solid lines). The black circle on the depth trends represent the
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53 approximate top Snadd Formation. As expected, both V_p trends for sand and shale increase as a
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3 function of depth due to increasing mechanical (stress dependent) and chemical (temperature and
4 time dependent) compaction with burial. The porosity loss with increasing burial depth is also
5 captured in the inverse relationship between V_p and PHIE. The end-member trends for P-
6 impedance and Poisson's ratio (ν) become more unique at burial depths greater than that
7 represented by the Snadd Formation. The V_p – Rho relationship is more unique (better end-member
8 separation) than the $V_p - V_s$ trend.
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11 The stochastic forward modelling results for different fluid scenarios using the end-member depth
12 trends as input are shown in Figure 6. The impact of compaction with increasing burial depth on
13 fluid discrimination is illustrated using the Gaussian ellipses and 1D PDFs for AI and V_p/V_s ratio.
14 Gaussian models are compared for brine, oil, and gas-filled sands with a 75% NTG. The centre of
15 each Gaussian ellipse represents the mean for the class. The distance from the mean to the edge of
16 the ellipse is equivalent to two standard deviations. At both modelled depths (1000 m and 2000 m
17 TVD ML), there is a significant overlap of the different fluid scenarios. The V_p/V_s ratio shows
18 better discrimination compared to AI at both depth intervals. With increasing burial depth (i.e., at
19 2000 m TVD ML), we observe that the ellipses for the different fluid scenarios overlap much more.
20 This is as expected because the rock framework becomes stiffer and it is more challenging to
21 determine the pore fluid content. Such an analysis should be done for target reservoirs with
22 contrasting burial depths such as the Snadd Formation, in order to determine the best set of elastic
23 parameters to be used for interpretation at different depths of investigation. For very heterolithic
24 formations with multimodal facies characteristics, the Gaussian assumption might be inadequate
25 and non-parametric multivariate PDFs derived from point density contours in elastic space are
26 more appropriate.
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3 Figure 10 shows the RGB spectral blending flattened top Snadd Formation using iso-frequencies
4 (11, 25, and 55 Hz for Red, Green, and Blue, respectively) decomposed from the full stack data
5 through a Fourier transform operation. These frequencies were selected based on the dominant
6 frequency and slope changes in the amplitude spectrum. The dominant frequency from the spectral
7 analysis is ~ 25 Hz. Some large – scale trends can be observed with the hot colours on the map.
8 These bright yellow-red trends are interpreted to represent higher NTG intervals after comparing
9 with the lateral NTG observed at the wells. A strong anomaly around Well-D corresponds with the
10 anomalous sand proportion within the top of the Snadd Formation in the relay ramp area (Figure
11 3a). Most of the large – scale trends in the northern part of the study area have a NNE orientation
12 (marked with dotted blue lines in Figure 11), except around Well-D with an almost E-W trend.
13 Meanwhile in the southwestern part of the study area the dominant trend changes to ENE. The
14 regional progradation of sediments from the Polar Urals was oriented SE-NW, but some local
15 variations may have occurred around the study area in the Southern Hammerfest Basin (Glørstad-
16 Clark et al., 2010; Klausen et al., 2014). Meanwhile, the E-W trends likely correspond with a
17 locally sourced trend. The branching points along the TFFC (indicated with arrows in Figure 10)
18 show some strong red anomalies with geometries consistent with point-sourced lobes where this
19 major fault branches. The E-W trends and the anomalies tied to the TFFC might be indications of
20 minor local Late Triassic tectonic activity along this master fault (Mulrooney et al., 2017).
21 However, the fidelity of the flattening process is questionable in areas with dense faulting, which
22 limits the resolution of the extracted anomalies, especially when dealing with very thin sands. A
23 closer look into the details in a fault segment with less structuring reveals finer details of what we
24 interpret to be a meandering channel, with a point bar complex. The width of these point bar
25 complexes approximately range between 200 – 250 m. In a low NTG environment distal from the
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3 main source area, it is expected that the channels will develop mud-rich and stable levees, which
4 help in confining the channel and therefore limiting the avulsion frequency. A schematic
5 representation of the meander channel and point bar complex is also shown in Figure 11.
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10 From a qualitative point of view, the seismic-to-well tie within the Snadd Formation is higher at
11 the top and base of the formation. However, it is important to quantitatively assess the fit by
12 examining the PEP and cross correlation over the interval of interest. In the example shown within
13 Track 9 in Figure 12, the PEP is 78 % and the cross correlation is 88 % thus representing a good
14 fit over the target zone.
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23 Figure 11 also shows the comparison between the well logs and the results from both the facies –
24 based Bayesian inversion and the neural network PHIE prediction at the reference well. The well
25 log curves are shown in black, the predicted logs in red, and the blocky red logs within the same
26 track represent the combined facies LFM output. There is a fairly good match between the inverted
27 logs and the actual logs, especially for the thicker sand intervals. In contrast to a model-based
28 deterministic inversion (with the LFM constructed from structurally guided well interpolation),
29 the QC is not compromised because the LFM is not supplied but computed during the inversion.
30 The difference (i.e., residuals) between the inverted traces and the actual seismic trace are also
31 shown in Track 12 in Figure 11 for visual comparison.
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44 The limitations in the seismic bandwidth and the effects of upscaling are more apparent when
45 comparing the derived facies model (Track 7) to the unscaled (Track 5) and upscaled well log
46 facies (Track 6) presented in Figure 11. In this example, there is a good match in the predicted
47 sand units approximately ≥ 15 m. The prior probability for reservoir sand and non-reservoir (Track
48 8) within the upper part of the Snadd Formation was set as equal. Some smoothing was applied to
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3 the prior probabilities (seen as a step pattern on the prior probability curves) to account for
4 gradational facies changes. In addition, the prior probability for reservoir sand is set to decrease
5 towards the base of the Snadd Formation; this is consistent with geologic prior information about
6 the vertical NTG distribution in the available wells. As expected, sand units smaller than 10 m are
7 hardly present in the upscaled facies log and are equally not detected in the inverted facies model.
8 The final facies result is the maximum a posteriori (MAP) facies or most likely facies. In this
9 binary system (reservoir and non-reservoir), this implies a facies probability greater than 50%.
10 However, if more than two facies are being inverted for, it is important to remember that the MAP
11 facies in the Bayesian classification could have a probability as low as 34%.

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25 Figure 12a shows the training (black curve) and validation error (red curve) profiles for a multi-
26 attribute analysis performed to determine the optimum set of attributes to use further in the neural
27 network. Table 2 contains the final list of 10 attribute transforms used. The combined shear
28 Impedance (SI) LFM from the inversion showed the best individual correlation to PHIE. A well-
29 known problem for neural networks is the potential to over classify the training data set. One way
30 to address this challenge is to start the analysis with a multi-attribute set that results in the smallest
31 validation error (i.e., the lowest turn around point in the validation error profile). The average
32 training error for all wells decreases with successive addition of attributes to the analysis. The
33 lowest minima in the validation error profile occurs at the 10th attribute transform. Each data point
34 on the validation error is obtained leaving out a target well in the analysis and using the other wells
35 to predict the desired property. If more than 10 attributes are used, the prediction quality starts to
36 decrease and we start over classifying the data, i.e., the point at which the average well training
37 error keeps reducing while the validation error progressively increases.

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3 Figure 12b shows a cross plot between the neural network predicted PHIE and actual PHIE log for
4 five wells. The cross correlation between them is 0.67. This plot highlights the underlying
5 challenge in predicting thin, below-resolution clean sand intervals. This challenge is common to
6 the inversion and the neural network result. The prediction does not fully capture the upside in the
7 PHIE estimates. No predicted PHIE data points are observed above 0.2. This is partly due to the
8 sampling rate (4 ms) used in the training which is rather coarse (i.e., for thin high PHIE sand
9 intervals within the Snadd Formation), but consistent to the seismic sampling rate. Track 4 in
10 Figure 11 shows the comparison between the neural network predicted log (red) and the well log
11 (black). The predicted log fully captures the PHIE trend in the log, and is consistent with the
12 inverted facies (Track 7) at the well location.
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27 An arbitrary line (Figure 13) through the reference well and a blind deviated well (i.e., well neither
28 used in the depth trend for the inversion nor in the training for PHIE) validates the inversion and
29 neural network results away from well control. In Figure 13a, the low AI layers correlate well to
30 reservoir sand facies (Figure 13b) with relatively higher PHIE (Figure 13c) within the upper part
31 of the Snadd Formation. The quality of the facies prediction can be quantified using a confusion
32 matrix. The off-diagonal elements in the matrix indicate the degree of error. The confusion
33 matrices for both wells are displayed in Figure 13b below the corresponding well. For the reference
34 well, the facies aware inversion correctly classifies the reservoir facies of interest 87.5 % of the
35 time and wrongly classifies it as non-reservoir 12.5 % of the time. The facies prediction for the
36 deviated blind well, which was not included in defining the facies depth trends, is also shown. The
37 reservoir sand prediction success is 65.38 %. This well has thinner sand units compared to the
38 reference well, and this could be one reason for a lower classification success. In reservoirs where
39 the facies do not show separate clusters in a rock physics space, the wavelet scaling becomes more
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3 crucial to the inversion result. However, the White (1980) method provided the appropriate
4
5 wavelet scaling required in our case. Notice that the middle to lower section of the Snadd
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7 Formation (Figure 13c) is dominated by PHIEs < 0.1 and is correctly classified as non-reservoir
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9 (Figure 13b) in the facies-based inversion. Despite the upside limitation in the predicted PHIE
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11 result, it is still very useful in a qualitative sense when combined with the inverted facies, to
12
13 highlight the cleanest intervals within the predicted reservoir sands in the upper parts of the Snadd
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15 Formation.
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20 Figure 14 shows a horizon slice for PHIE and facies at the top of the Snadd Formation interval.
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22 The ovals and arrows from the RGB flattened slice in Figure 10 are shown for a visual qualitative
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24 comparison between the attributes. The extent of the anomalies indicating gross depositional trends
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26 (Figure 10) are much larger than observed in the PHIE (Figure 14a) and Facies (Figure 14b)
27
28 horizon slices. In general, there is consistency between the PHIE and Facies horizon slices with a
29
30 few exceptions. The large white ovals in Figure 14 show areas with predicted reservoir sand but
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32 with very low porosity predictions. This could be interpreted to represent more cemented sands,
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34 as this area structurally lower (easily seen in Figure 3b around the grey arrow) within a graben
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36 structure bounded by relay ramp faults. The combined map (Figure 14c) showing the clean sand
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38 geobodies represent predicted sand facies with PHIEs $> 15\%$. Artefacts are produced along the
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40 faults in both the facies and PHIE maps and reliability of the maps increase away from the faults.
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49 CONCLUSION

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52 Properly constrained facies-dependent rock physics depth trends are very important for successful
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54 quantitative seismic reservoir characterisation within the Snadd Formation in the Goliat field.
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3 However, if these trends are to be used in other parts of the SW Barents Shelf, an appropriate
4 reference depth needs to be thoroughly investigated before hanging the depth trends in areas with
5 seismic data but no wells. Fluid sensitivity is shown to decrease with depth based on the PDFs
6 obtained from the end member trends. Spectral decomposition and RGB blended results reveal
7 two main depositional trends: i) a NNE trend compared to the SE – NW regional clinoform
8 progradation of sediments from the Uralide orogeny, and ii) an E-W local trend which likely
9 represents local sources tied to pulses of sediments at branching points of the TFFC. The Snadd
10 Formation is strongly compartmentalised so the fidelity of the flattened slice is uncertain in
11 intensively faulted areas.
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24 Despite the considerable overlap of the binary facies in a rock physics elastic space, the facies-
25 aware Bayesian inversion is still able to largely discriminate reservoir sands from non-reservoir at
26 a blind well (i.e., not used in the depth trend analysis). When inverting for more than two facies,
27 it is crucial to further investigate the probability of the most likely facies which can be as low as
28 26% (i.e., if four facies are inverted for).
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37 The neural network porosity predictions capture the general vertical trends in the wells, but do not
38 properly capture the very thin high PHIE sands. However, the PHIE results are consistent with the
39 inverted facies and can be used in a qualitative manner to discriminate the best reservoir facies
40 with high PHIE. Areas interpreted to represent point sources for sediment input along the TFFC
41 from the RGB flattened slice are supported by both facies and PHIE predictions. Neural networks
42 should be viewed as an additional tool to decode complex relationships in the data especially when
43 available linear and non-linear rock physics models fail.
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18 LIST OF FIGURES

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21 **Figure 1** Location map for the Goliat Field (adapted from NPD factmaps) in the Norwegian sector
22 of the Barents Sea. The field is cut by the Troms-Finnmark Fault Complex within blocks 7122/7
23 and 7122/8 (Yenwongfai et al., 2017a)
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29 **Figure 2** Triassic chronostratigraphic framework comparison (a) for different authors. The
30 subdivisions are based on 2nd and 3rd order sequences (Klausen et al., 2015). The Snadd Formation
31 (target in this study) is also starred. The vertical change in the net-to-gross (as seen from the Sand
32 Flag log track) effectively divides the interval into three main lithological zones (b). Zone 1 has
33 thicker more consistent sand units. Meanwhile zone 2 and 3 have heterolithic sands and shales
34 respectively. Maximum flooding surfaces (MFSs) bounding the top and base of the Snadd
35 Formation are also indicated. The P-impedance log is superimposed on the full stack seismic
36 section. Note that positive amplitudes on the seismic represent soft events.
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48 **Figure 3** Well correlation profile from north to south. Well-D has an anomalous high sand
49 proportion within the Snadd Formation and is located within a relay ramp structure (black arrow).
50 Well-D is a side track from Well-G (not visible in Figure 3b) and deviates further away from Well-
51 G below the top Snadd Formation horizon. Minor faults around both wells might explain
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3 differences in the observed NTG. Gamma log motifs from Well-B show good examples of stacked
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5 fining upward channels bounded by flooding surfaces.
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8 **Figure 4** Workflow implemented for petrofacies and PHIE characterisation within the Snadd
9 Formation. Depth trends play a central role in the feasibility study and during the inversion. The
10 flow diagram shows the routes to clean sand delineation. The five main steps in the seismic
11 reservoir characterisation workflow are highlighted in green.
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18 **Figure 5:** End-member depth trends for sand and shale through the whole well interval. The V_p ,
19 V_s , ρ , and PHIE trends are the primary trends (a) while the other trends (b) are derived from
20 the primary trends. The sand-end member trends have been Gassmann fluid substituted to brine.
21 The black circle shows the approximate depth location of the top Snadd Formation.
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28 **Figure 6:** Depth varying PDFs (a) based on stochastic forward modelling of the end-member
29 trends (shown in Figure 5). The plots show the fluid discrimination of AI and V_p/V_s attributes as
30 a function of depth. Sensitivity decreases with depth as shown by increasing overlap of each ellipse
31 and PDFs. Also the effective extended elastic impedance (EEI) chi angle (c) using the depth trends
32 are also shown. The black and red arrows indicate the effective lithology and fluid angles.
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41 **Figure 7** AI versus V_p/V_s cross plots colour coded with Vsh (a) and PHIE (b). The contour density
42 for sand and shale are based on a PHIE cut-off using 12% as the threshold. Sands dominate at low
43 AI and V_p/V_s ratios. However, the histograms still show a significant overlap of both facies.
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48 **Figure 8** Reservoir and non-reservoir depth trends within the Snadd and kobbe Formation time
49 interval. These depth trends (a) provide the uncertainty distribution (standard deviation of the
50 derived trend curve) of the elastic properties as a function of depth as well as the cross correlation
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3 and constraints between the elastic parameters per facies. A cross plot comparison (b) between the
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5 prior model derived from the depth trends and the corresponding well data are also shown.
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8 **Figure 9** Wavelet processing and spectral analysis. The near, mid, and far angle stack wavelets (a)
9
10 have all been extracted using the White (1980) method. The wavelets have been extracted based
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12 on the offset location with the highest PEP close to the well bore. The signal and noise spectra (b)
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14 at the top of the Snadd Formation interval are also shown with the selected frequencies used in the
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16 RGB blend.
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20 **Figure 10:** Spectral decomposition and RGB blending of selected frequencies displayed at the top
21
22 Snadd Formation flattened horizon slice. The corresponding frequency spectra (Figure 9b) is also
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24 inserted for reference to the frequencies. The bright red arrows show a dominant NNE trend.
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26 Meanwhile close to the branching points along the Troms-Finnmark Fault Complex (TFFC),
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28 observed anomalies are oriented E – W (black dotted lines). The white dotted lines, show the
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30 anomaly around Well-D (anomalous sand proportion in Figure 3) indicated with a blue arrow. A
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32 detailed view around Well-E shows a schematic representation of a channel and point bar complex.
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34 Note that Well-E just sits at the edge of this anomaly.
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40 **Figure 11:** Facies-aware inversion and neural network results at the reference well. The inverted
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42 elastic logs (blue logs in Track 2 and 3) are plotted alongside the LFM (low frequency model)
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44 output logs (red logs) in the same tracks. There is a good match between the inverted facies log
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46 (Track 7) compared to the upscaled (Track 6). The inversion synthetic logs and the residuals are
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48 also shown in Track 11 and Track 12. The predicted PHIE log (red) from the neural network shows
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50 a match to the thicker and better developed reservoir sands (above 1240 ms TWT).
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3 **Figure 12** Multi-attribute neural network training (a) and prediction correlation (b). The validation
4 error is shown to increase after the 10th attribute transform in the multi-attribute analysis. Attribute
5 number 1 – 10 are used in the neural network prediction. We refer the reader to Table 2 for more
6 details in Figure 12a.
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13 **Figure 13** Arbitrary line section through the reference well (Well-A) and the blind well (Well-C).
14 The simultaneous Bayesian Joint Impedance (a) and Facies (b) inversion results are compared with
15 the neural network PHIE predictions (c). Good PHIEs observed at the upper part of the Snadd
16 Formation (results from the neural network) are consistent with the predicted reservoir sands from
17 the inversion. The quality of the facies predictions are illustrated in a confusions matrix below the
18 respective wells. Diagonal elements in the matrix indicate the degree of success of the
19 classification.
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30 **Figure 14** Horizon slices at the top of the Snadd Formation for effective porosity (a) and binary
31 facies (b) over a 30ms window. The binary facies map is the result from the facies-based inversion,
32 while the the porosity map is the output from the multi-layer feedforward neural network. The
33 clean sand geobodies (c) represent predicted reservoir sand facies with PHIE greater than 15 %.
34 Reservoir delineation is improved by qualitatively combining areas with good effective porosity
35 in regions where reservoir sand is predicted by the inversion. The arrows and ovals from the
36 flattened RGB slice in Figure 10, are inserted for visual comparison.
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LIST OF TABLES

Table 1: Grain and fluid properties used as input for brine substitution of the sand end-member trend through Gassmann's equation. Quartz properties have been used for sand end-member grain properties.

Table 2: Multi-attribute transform list used as input to the neural network. Attribute numbers correspond to numbers used in Figure 13a. The attribute transform with the highest individual correlation to PHIE, is the Shear Impedance (SI) LFM output constructed during the inversion. Note that the errors associated with each successive attribute is cumulative by applying all preceding attributes.

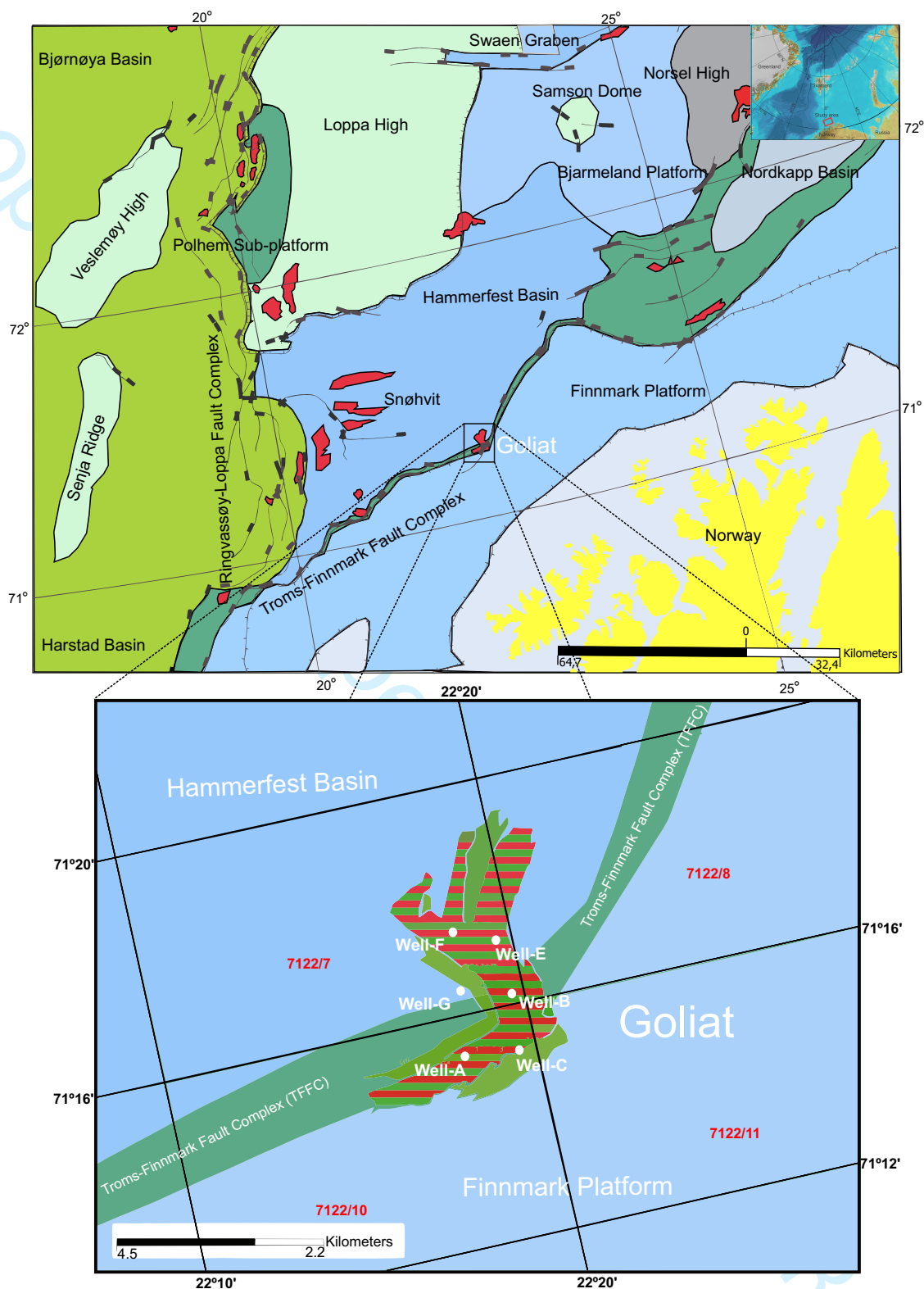


Figure 1 Location map for the Goliat Field (modified from NPD factmaps) in the Norwegian sector of the Barents Sea. The field is cut by the Troms-Finmark Fault Complex within blocks 7122/7 and 7122/8 (Yenwongfai et al., 2017a)

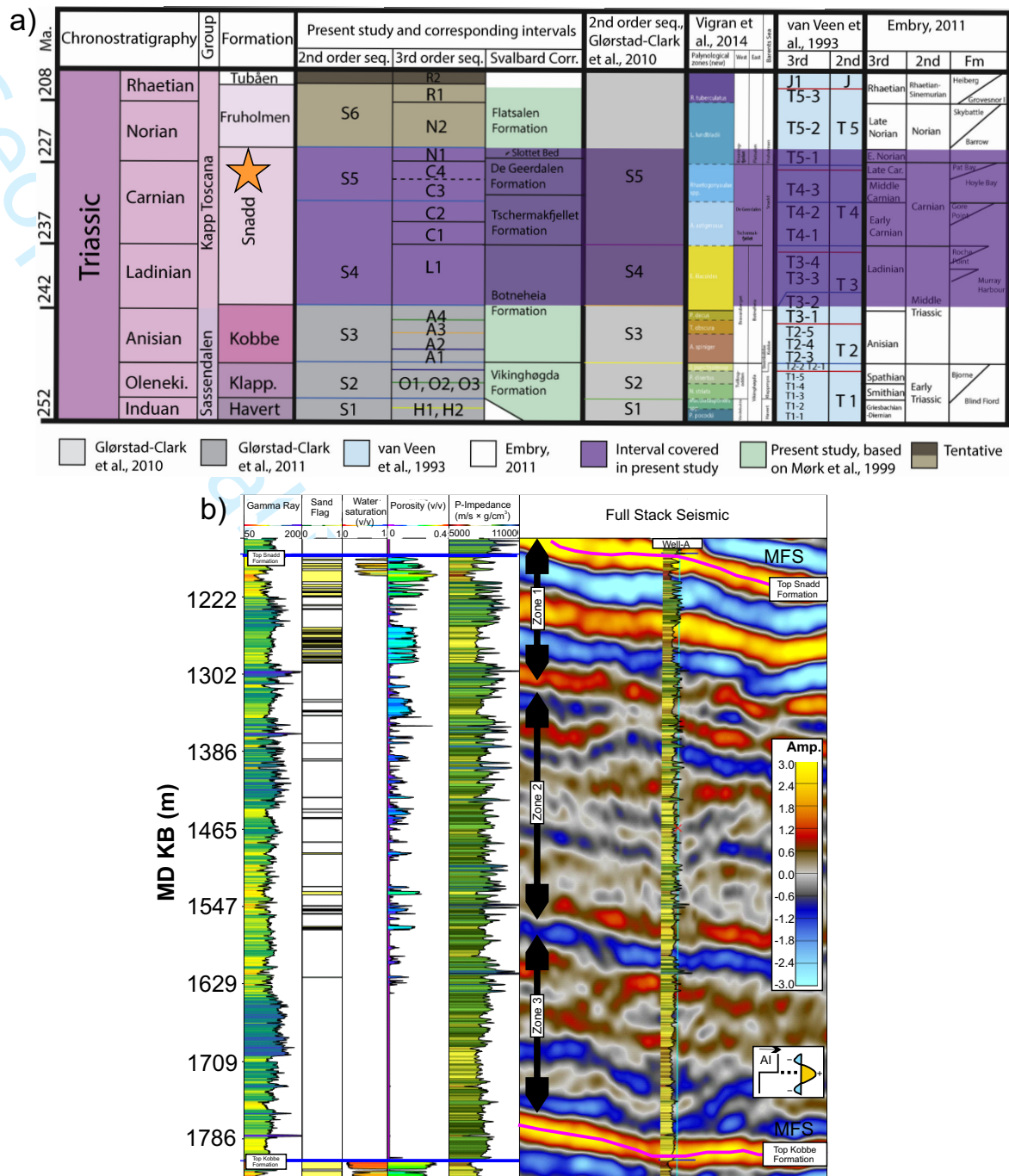
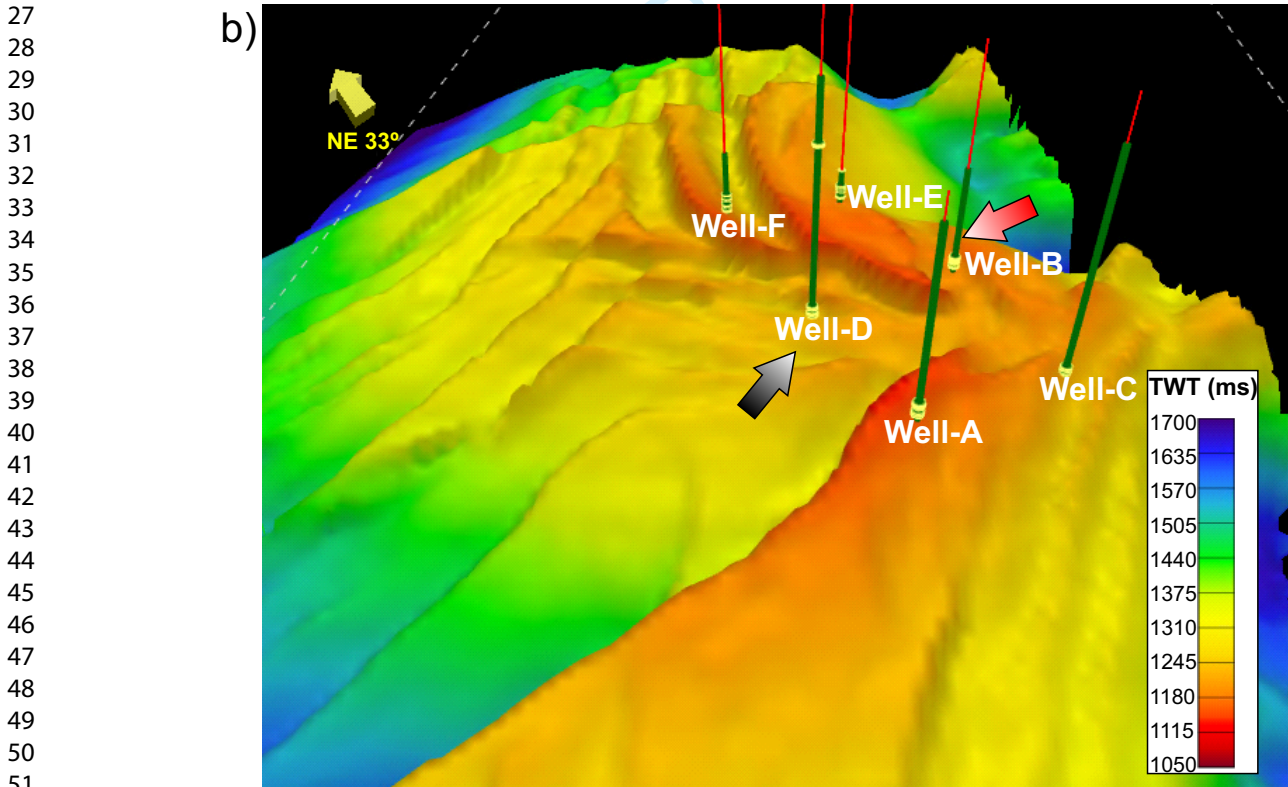
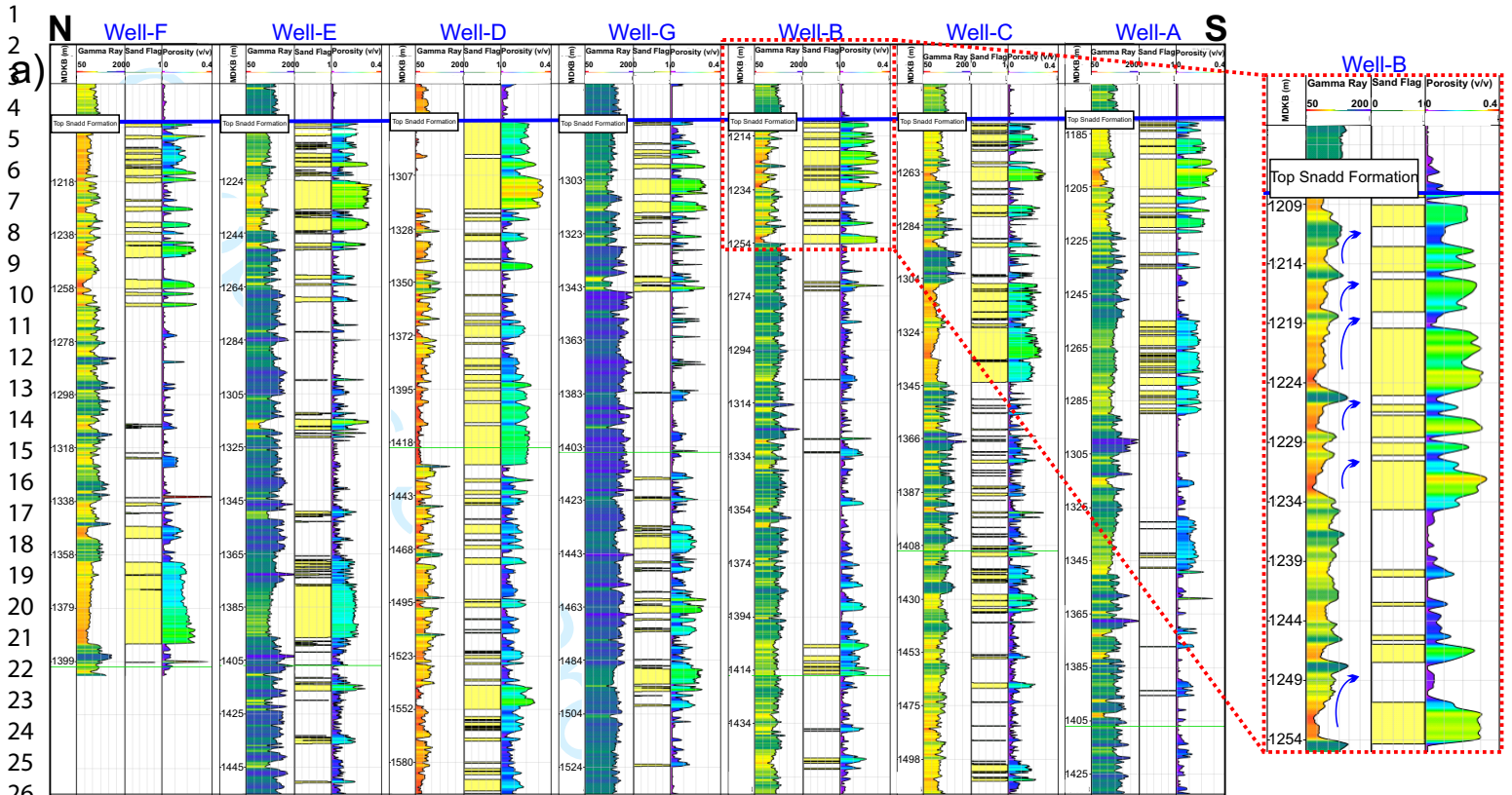


Figure 2 Triassic chronostratigraphic framework comparison (a) for different authors. The subdivisions are based on 2nd and 3rd order sequences (Klausen et al., 2015). The Snadd Formation (target in this study) is also starred. The vertical change in the net-to-gross (as seen from the Sand Flag log track) effectively divides the interval into three main lithological zones (b). Zone 1 has thicker more consistent sand units. Meanwhile zone 2 and 3 have heterolithic sands and shales respectively. Maximum flooding surfaces (MFSs) bounding the top and base of the Snadd Formation are also indicated. The P-impedance log is superimposed on the full stack seismic section. Note that positive amplitudes on the seismic represent soft events.



3D time structure map with available wells

Figure 3 Well correlation profile from north to south. Well-D has an anomalous high sand proportion within the Snadd Formation and is located within a relay ramp structure (black arrow). Well-D is a side track from Well-G (not visible in Figure 3b) and deviates further away from Well-G below the top Snadd Formation horizon. Minor faults around both wells might explain differences in the observed NTG. Gamma log motifs from Well-B show good examples of stacked fining upward channels bounded by flooding surfaces.

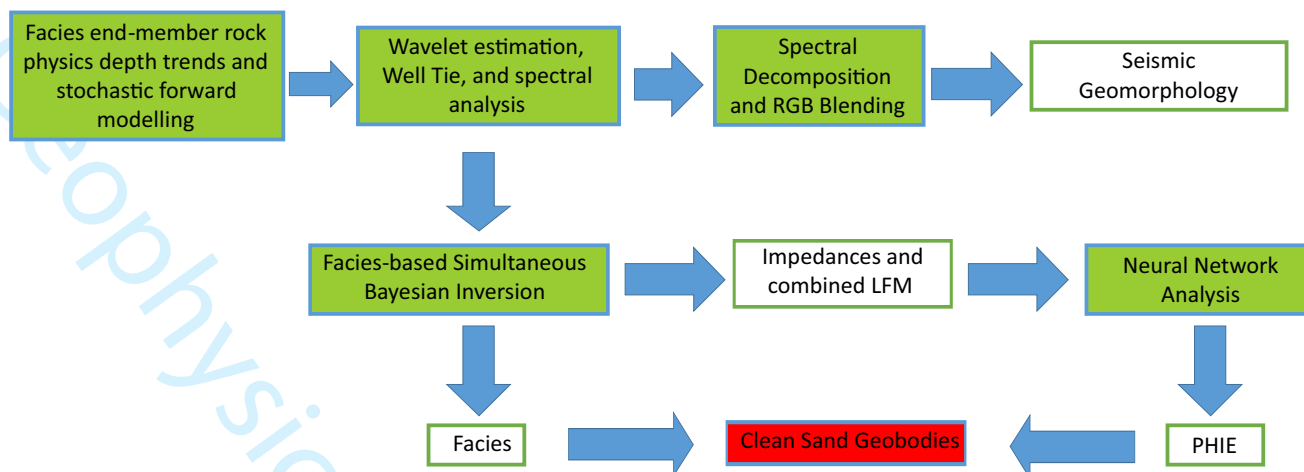


Figure 4 Workflow implemented for petrofacies and PHIE characterisation within the Snadd Formation. Depth trends play a central role in the feasibility study and during the inversion. The flow diagram shows the routes to clean sand delineation. The five main steps in the seismic reservoir characterisation workflow are highlighted in green.

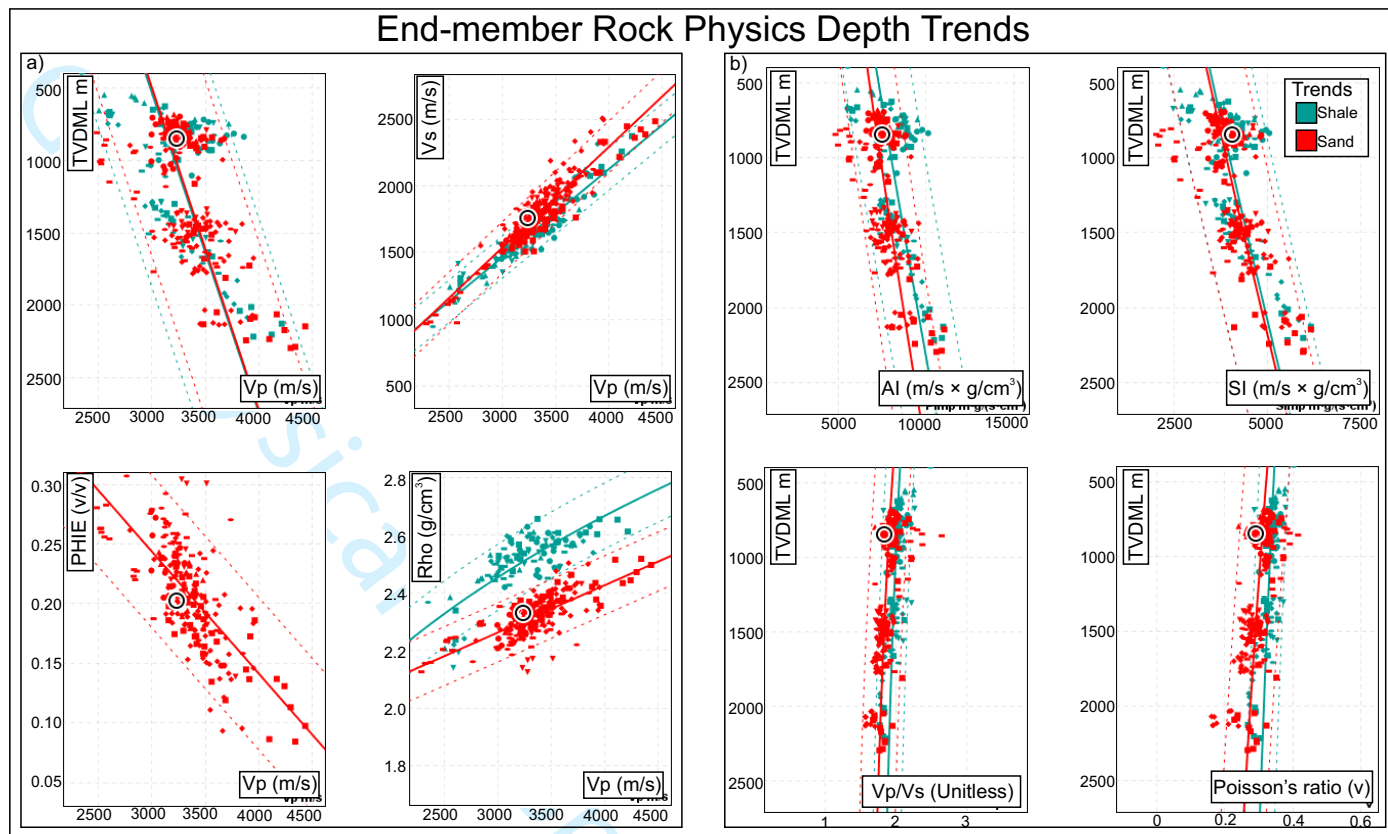


Figure 5: End-member depth trends for sand and shale through the whole well interval. The V_p , V_s , Rho , and $PHIE$ trends are the primary trends (a) while the other trends (b) are derived from the primary trends. The sand-end member trends have been Gassmann fluid substituted to brine. The black circle shows the approximate depth location of the top Snadd Formation.

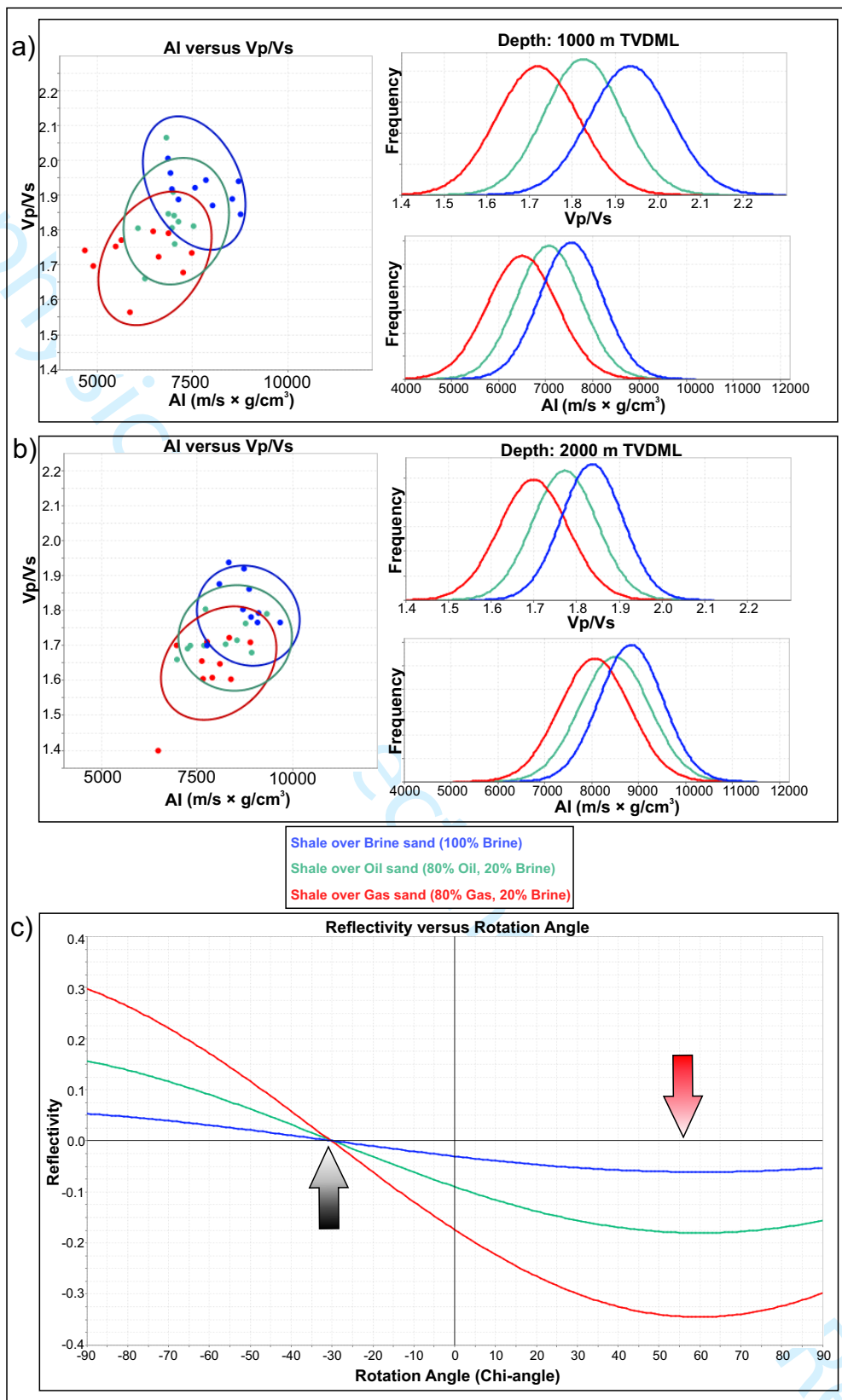


Figure 6: Depth varying PDFs (a) based on stochastic forward modelling of the end-member trends (shown in Figure 5). The plots show the fluid discrimination of AI and Vp/Vs attributes as a function of depth. Sensitivity decreases with depth as shown by increasing overlap of each ellipse and PDFs. Also the effective extended elastic impedance (EEI) chi angle (c) using the depth trends are also shown. The black and red arrows indicate the effective lithology and fluid angles.

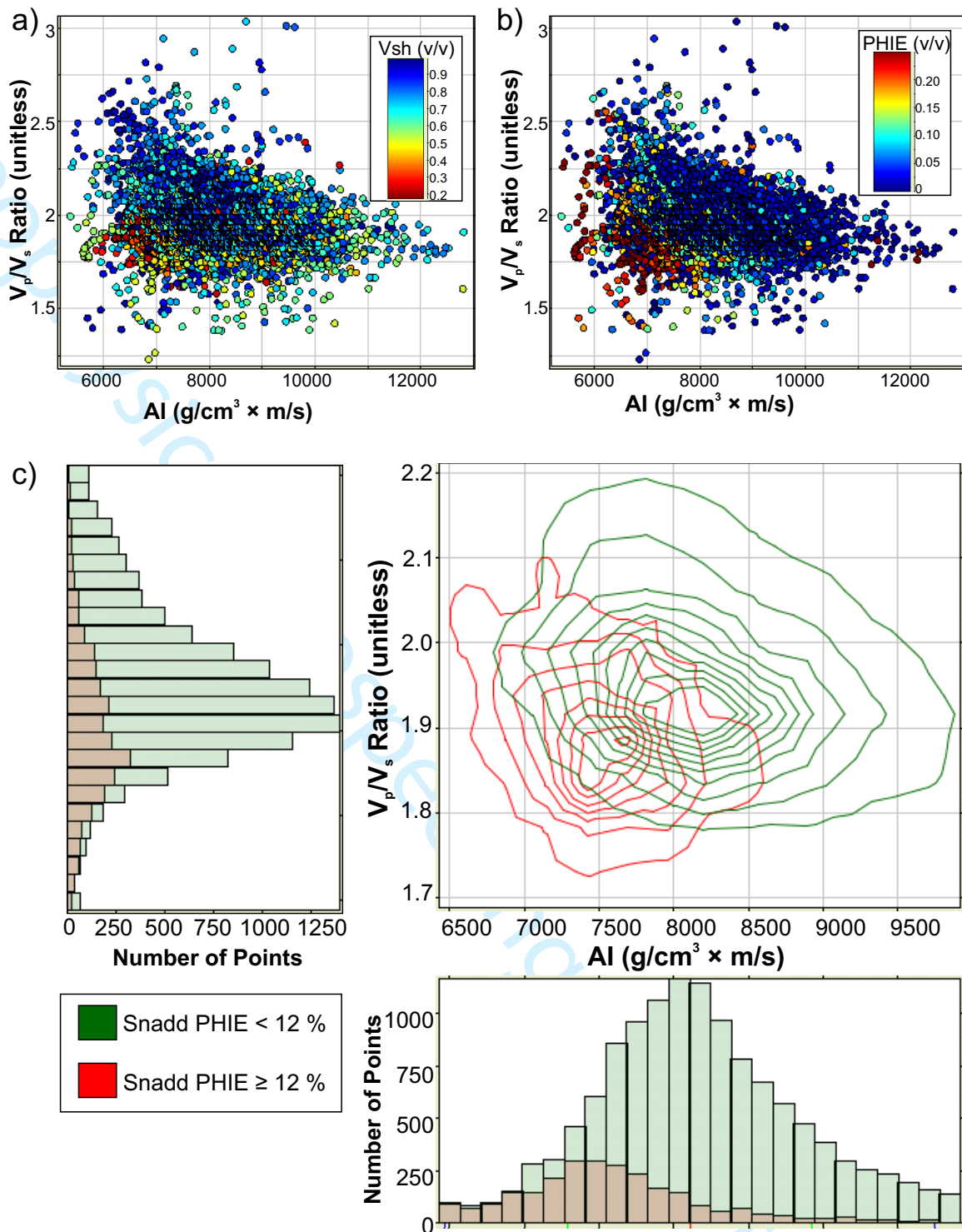


Figure 7 AI versus V_p/V_s cross plots colour coded with Vsh (a) and PHIE (b). The contour density for sand and shale are based on a PHIE cut-off using 12% as the threshold. Sands dominate at low AI and V_p/V_s ratios. However, the histograms still show a significant overlap of both facies.

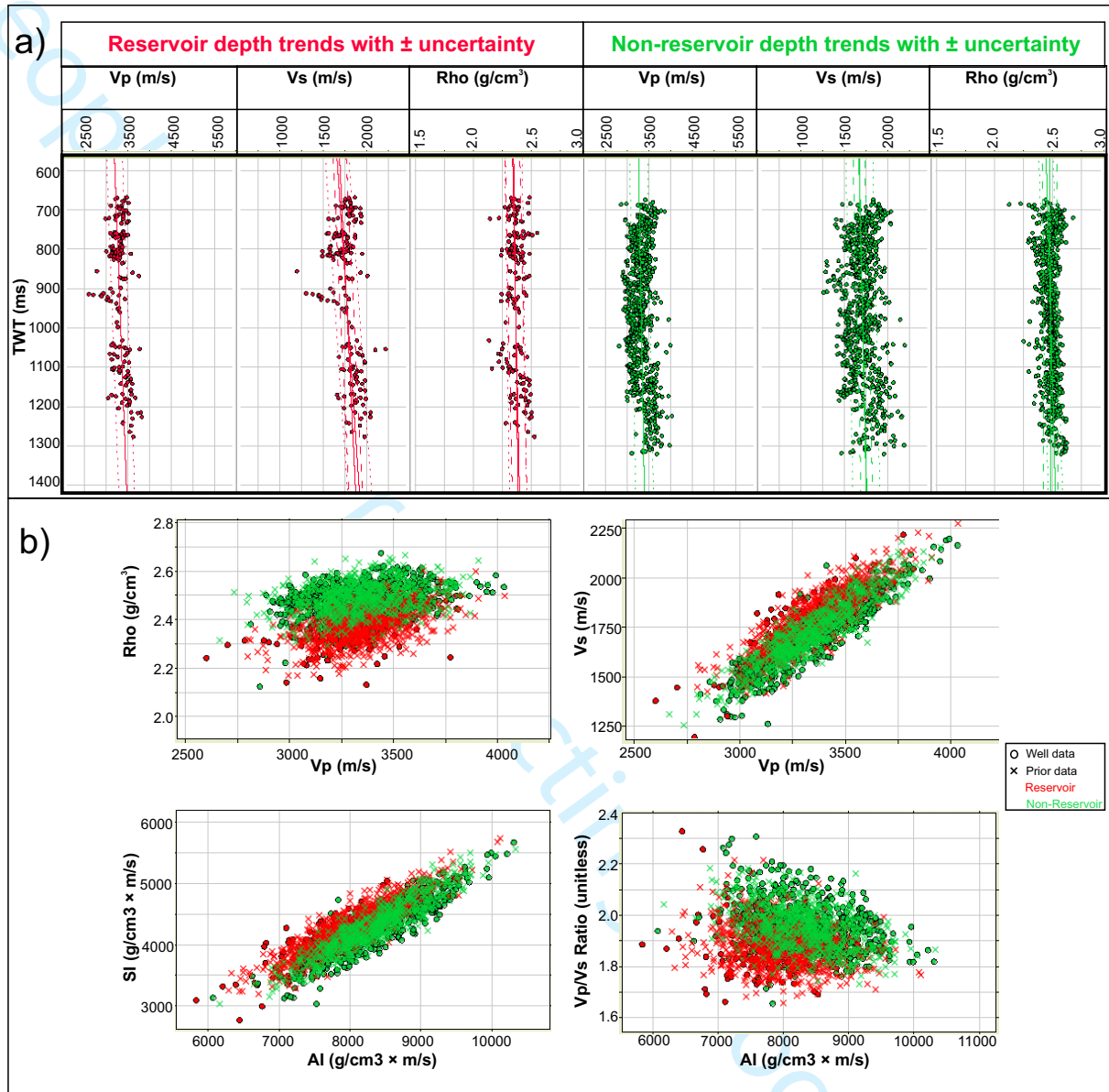


Figure 8 Reservoir and non-reservoir depth trends within the Snadd and Kobbe Formation time interval. These depth trends (a) provide the uncertainty distribution of the elastic properties as a function of depth as well as the cross correlation and constraints between the elastic parameters per facies. A cross plot comparison (b) between the prior model derived from the depth trends and the corresponding well data are also shown.

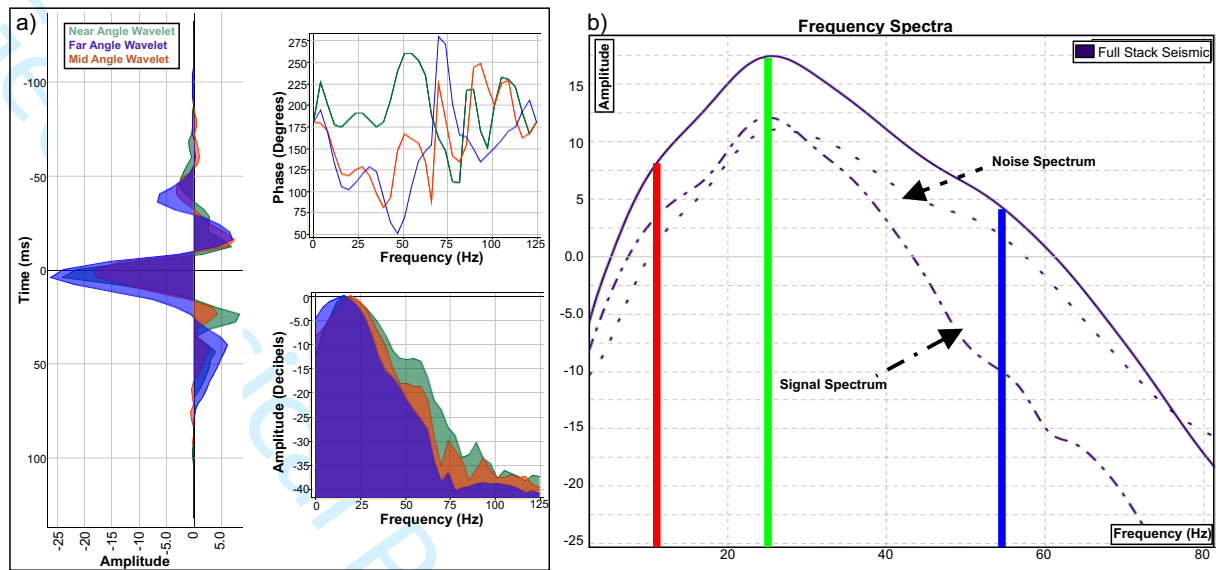


Figure 9 Wavelet processing and spectral analysis. The near, mid, and far angle stack wavelets (a) have all been extracted using the White (1980) method. The wavelets have been extracted based on the offset location with the highest PEP close to the well bore. The signal and noise spectra (b) at the top of the Snadd Formation interval are also shown with the selected frequencies used in the RGB blend.

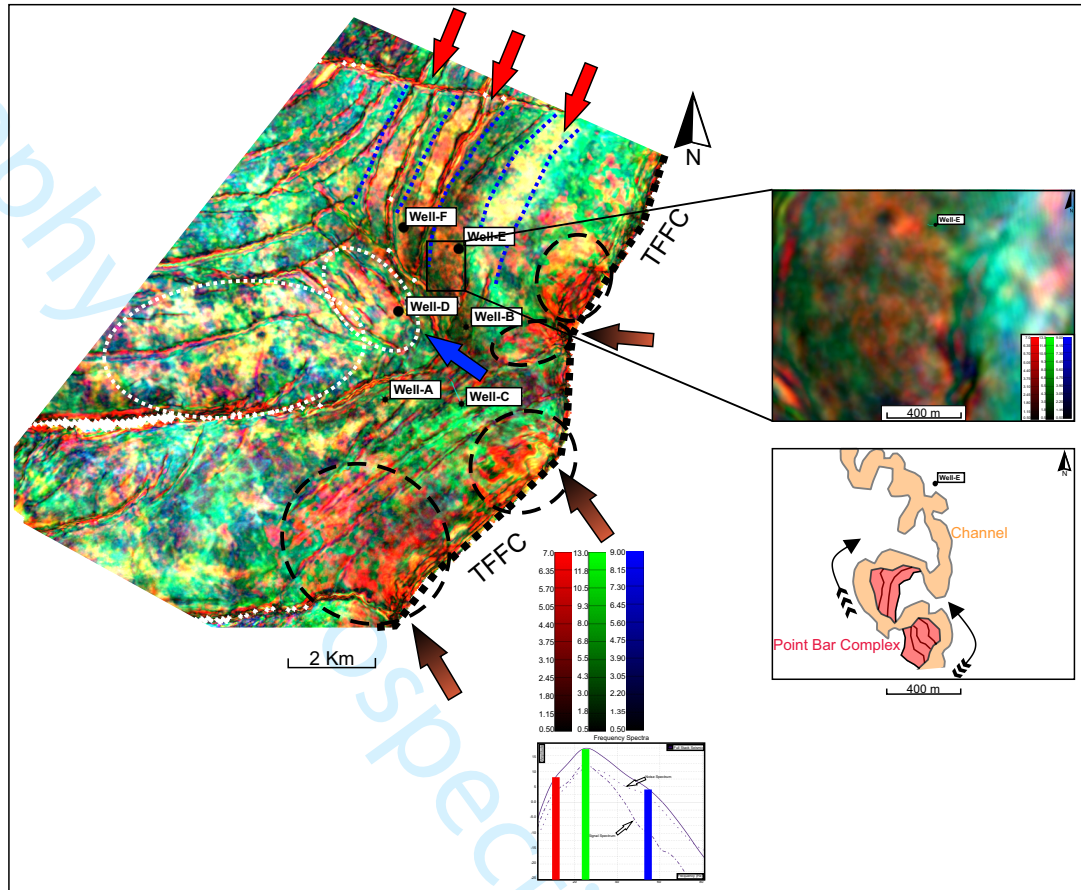


Figure 10: Spectral decomposition and RGB blending of selected frequencies displayed at the top Snadd Formation flattened horizon slice. The corresponding frequency spectra (Figure 9b) is also inserted for reference to the frequencies. The bright red arrows show a dominant NNE trend. Meanwhile close to the branching points along the Troms-Finnmark Fault Complex (TFFC), observed anomalies are oriented E-W (black dotted lines). The white dotted lines, show the anomaly around Well-D (anomalous sand proportion in Figure 3) indicated with a blue arrow. A detailed view around Well-E shows a schematic representation of a channel and point bar complex. Note that Well-E just sits at the edge of this anomaly.

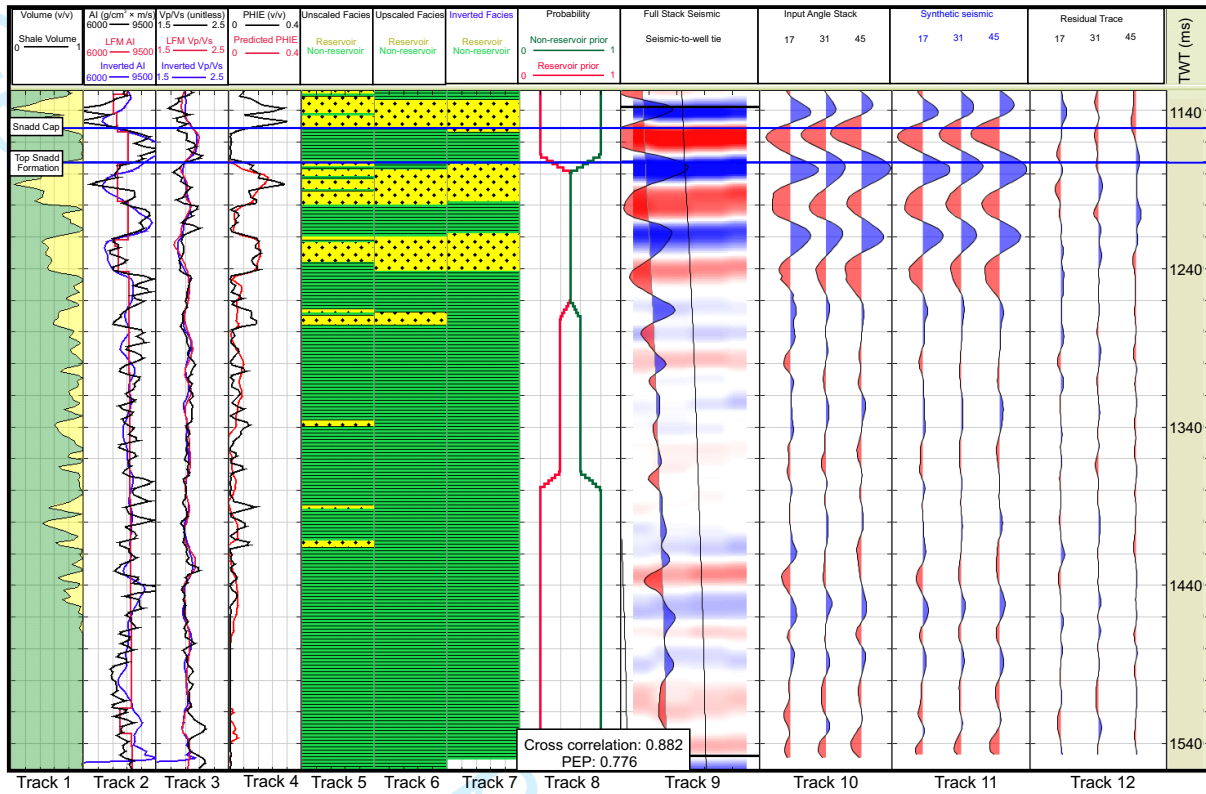


Figure 11: Facies-aware inversion and neural network results at the reference well. The inverted elastic logs (blue logs in Track 2 and 3) are plotted alongside the LFM (low frequency model) output logs (red logs) in the same tracks. There is a good match between the inverted facies log (Track 7) compared to the upscaled (Track 6). The inversion synthetic logs and the residuals are also shown in Track 11 and Track 12. The predicted PHIE log (red) from the neural network shows a match to the thicker and better developed reservoir sands (above 1240 ms TWT).

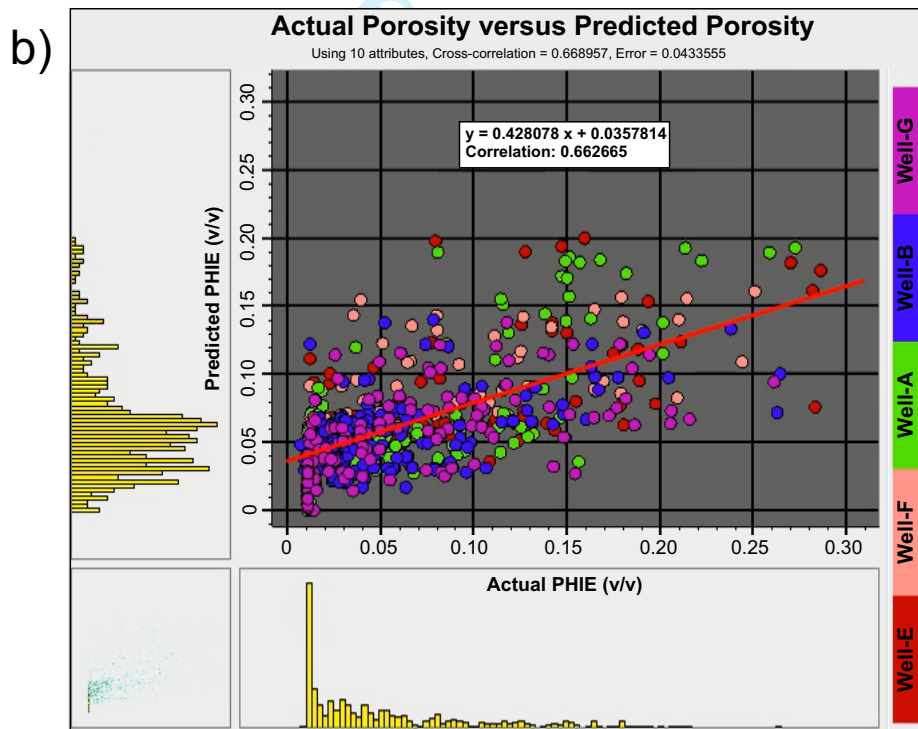
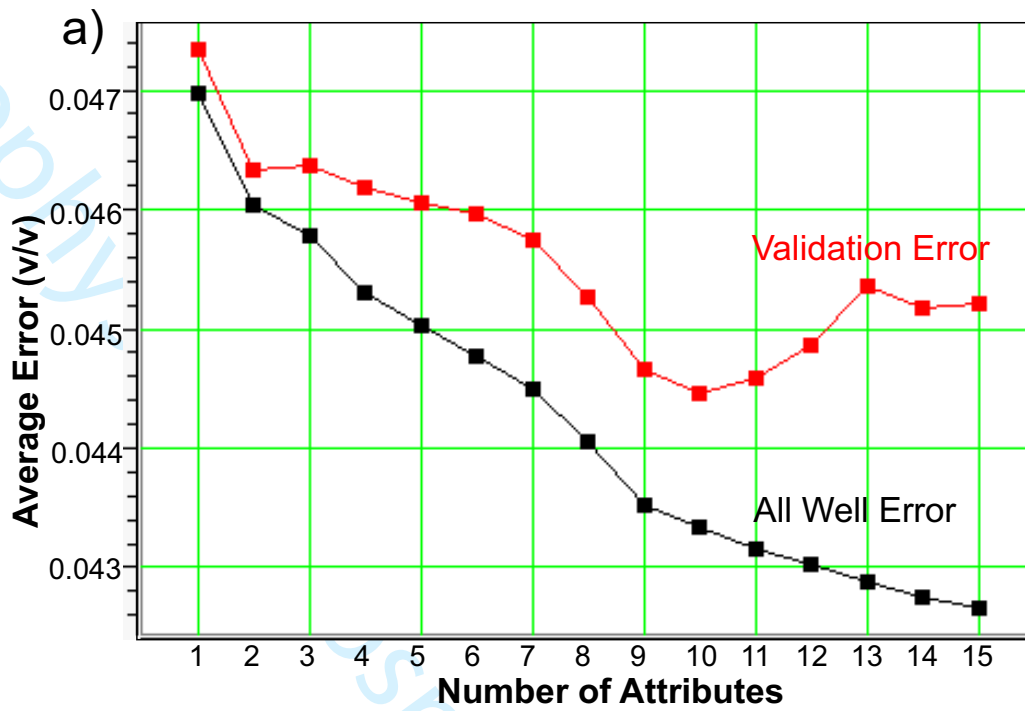


Figure 12 Multi-attribute neural network training (a) and prediction correlation (b). The validation error is shown to increase after the 10th attribute transform in the multi-attribute analysis. Attribute number 1 – 10 are used in the neural network prediction. We refer the reader to Table 2 for more details in Figure 12a.

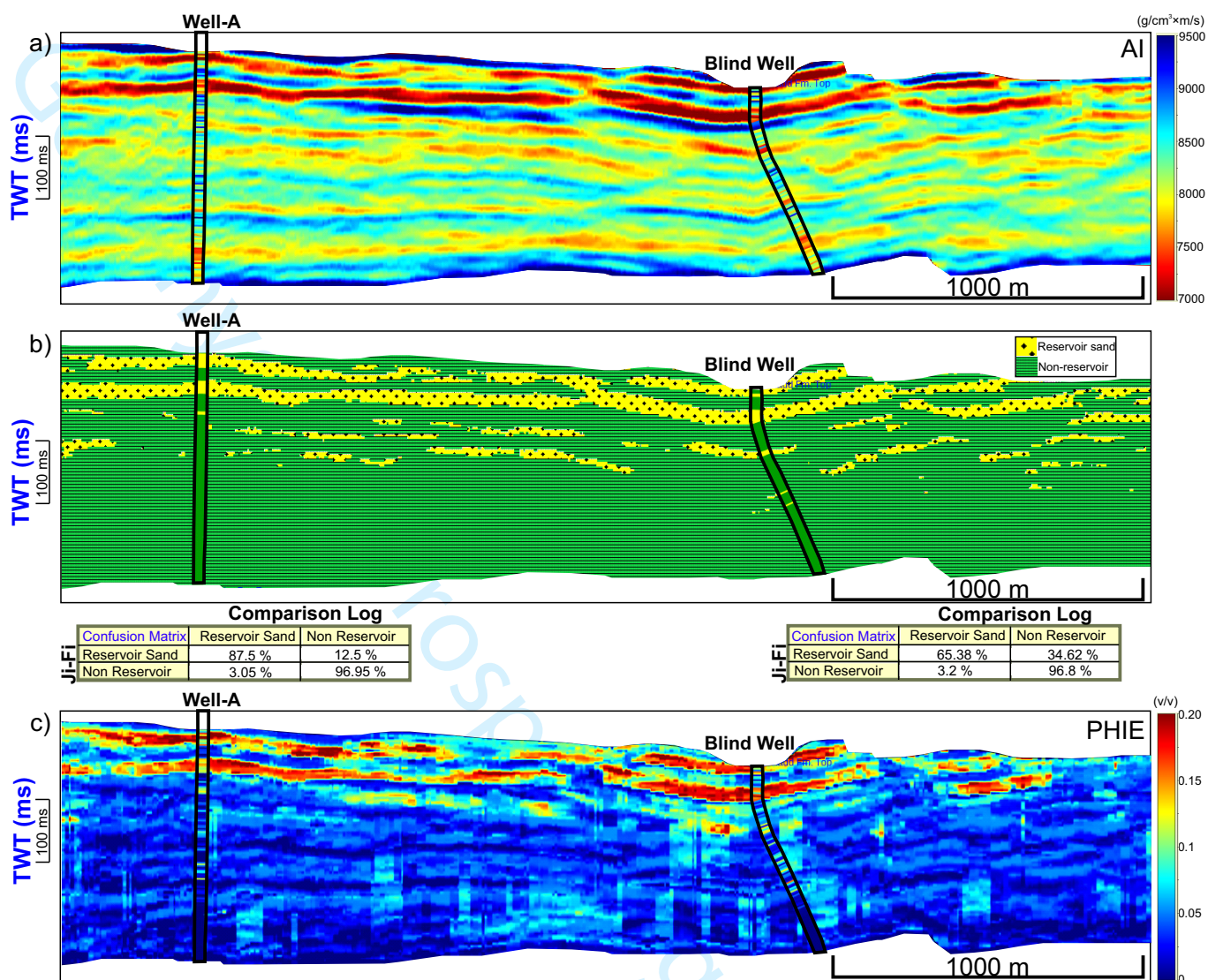


Figure 13 Arbitrary line section through the reference well (Well-A) and the blind well (Well-C). The simultaneous Bayesian Joint Impedance (a) and Facies (b) inversion results are compared with the neural network PHIE predictions (c). Good PHIEs observed at the upper part of the Snadd Formation (results from the neural network) are consistent with the predicted reservoir sands from the inversion. The quality of the facies predictions are illustrated in a confusions matrix below the respective wells. Diagonal elements in the matrix indicate the degree of success of the classification.

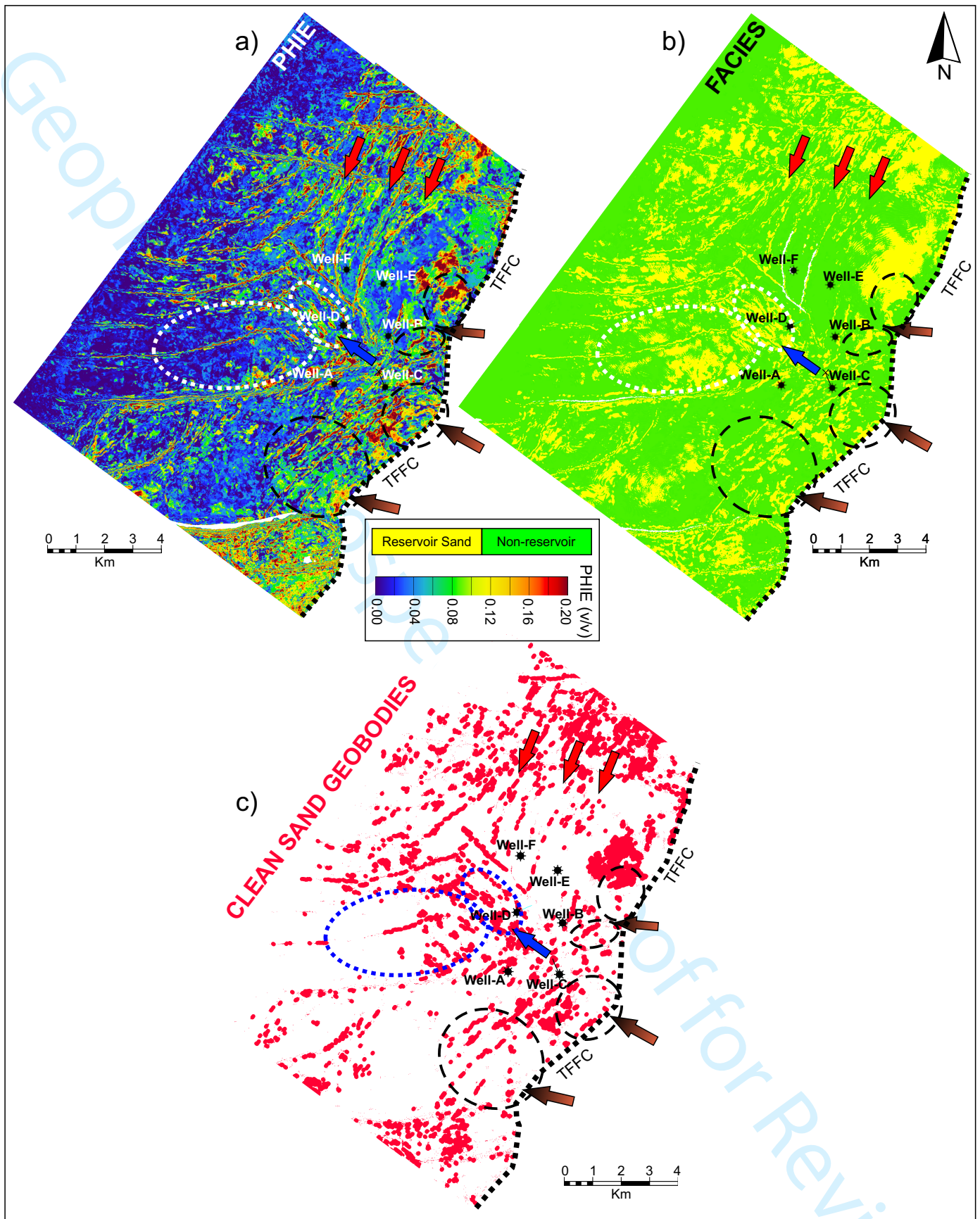


Figure 14 Horizon slices at the top of the Snadd Formation for effective porosity (a) and binary facies (b) over a 30ms window. The binary facies map is the result from the facies-based inversion, while the porosity map is the output from the multi-layer feedforward neural network. The clean sand geobodies (c) represent predicted reservoir sand facies with PHIE greater than 15%. Reservoir delineation is improved by qualitatively combining areas with good effective porosity in regions where reservoir sand is predicted by the inversion. The arrows and ovals from the flattened RGB slice in Figure 10, are inserted for visual comparison.

Grain/Fluid	Vp (m/s)	Rho (g/cm ³)	Vs (m/s)
Quartz	5960	2.65	3730
Brine	1500	1.05	
Oil	1100	0.8	
Gas	600	0.15	

Table 1: Grain and fluid properties used as input for brine substitution of the sand end-member trend through Gassmann's equation. Quartz properties have been used for sand end-member grain properties.

Attribute	Final Attribute Transform	Training Error	Validation Error
1	(SI LFM) ²	0.046991	0.047351
2	EEI (25°) Rotation	0.046058	0.046354
3	Derivative Instantaneous Amplitude	0.045795	0.046395
4	Filter 5/10-15/20	0.045328	0.046198
5	1/(Vp/Vs)	0.045039	0.046079
6	Dominant Frequency	0.044791	0.045984
7	Amplitude Weighted Phase	0.044515	0.045759
8	Amplitude Envelope	0.044082	0.045286
9	Second Derivative Instantaneous Amplitude	0.043540	0.044677
10	Quadrature Trace	0.043356	0.044485

Table 2: Multi-attribute transform list used as input to the neural network. Attribute numbers correspond to numbers used in Figure 13a. The attribute transform with the highest individual correlation to PHIE, is the Shear Impedance (SI) LFM output constructed during the inversion. Note that the errors associated with each successive is attribute is cumulative by applying all preceding attributes.

REPLY TO REVIEWER COMMENTS**Manuscript GP-2017-0155.R1**

Special Volume "Rock-physics - From microstructure to seismic signatures"

"Integrating facies-based Bayesian inversion and supervised machine learning for petrofacies characterisation in the Snadd Formation of the Goliat Field, SW Barents Sea."

Associate Editor

"I recommend a moderate revision. Please account for the comments of reviewer #2.

Some additional comments:

- **2nd sentence of Abstract is not understandable. Please rephrase.**
 - ✓ *The sentence has been rephrased to "This is especially important when the elastic properties of the desired petrofacies significantly overlap."*
- **Figure 12b: I suppose the predicted porosities with negative values can be excluded.**
 - ✓ *We have now disregarded the negative porosities and Figure 12b has been updated in the revised manuscript.*
- **Be consistent with acronyms. For example, PSDM is defined more than once in the text.**
 - ✓ *The second definition of PSDM has been deleted. Other acronyms in the text have also been double-checked for any repetitions.*
- **In many places the manuscript reads like a technical report. You often use "generally helps", "is usually done" or the like. This makes it hard for the reader to understand what your original contribution is, when you follow a standard workflow or when you use results of others. I would like to encourage you to use more active language.**
 - ✓ *Selected sections of the text have been rephrased with more active tenses. These changes can be seen in the annotated revised manuscript.*

Reviewer: 1

- **"I think the content of this paper qualifies for the publication. Please double check the citations in the text to match those in the references".**
 - ✓ *The in-text citations have been checked for consistency and five references were updated. These changes are highlighted in the revised manuscript.*

Reviewer: 2

Major comments

- **"If the main objective of a study is a combination of different sources of information to map out reservoir sands then I would expect such a final map to be presented by**

the authors or alternatively some information about how disagreements between the different sources of information would be handled to obtain such a final map”.

- A final map has now been included (Figure 14c) showing clean sand geobodies extracted based on the inversion-derived binary facies, and PHIEs from the neural network i.e reservoir sand prediction AND PHIEs >15% represent “clean sand geobodies in Figure 14c.
- **“A workflow for me implies that the results obtained in step 4 are used in step5. It needs to be clarified that this is not the case as stated by the authors in the reply to reviewers' comments”.**
 - **Step 5** “Supervised neural network for porosity estimation” uses the elastic parameters derived from **Step 4** “Facies-based Bayesian inversion to predict absolute elastic properties and facies”. This is also evident in the Final Attribute Transform list in **Table 2**. For example, **Attributes 1 and 5** are transforms of outputs derived from the facies-based inversion in **Step 4**.
 - With respect to the previous reply to reviewers' comments, We would like to clarify that the neural network has NOT been used to improve the elastic property prediction obtained from the facies-based inversion. Rather, the elastic properties from the inversion have been used as an input for the PHIE prediction in the neural network. We hope this explanation clarifies the workflow shown in Figure 4.
- **“It is also not clear why the full workflow consists of less steps than the summary workflow (Figure 4) and does not show the branching of the summary workflow”.**
 - The words “summary and full” have been removed from the caption in **Figure 4** and in the text. The 5 main processes listed in the text have now been given a different colour. In addition, the branching has been modified to hopefully provide better clarity. We hope this further clarifies the workflow figure
- **“Figure 2: The caption refers to a vertical change in net-to-gross. Is this the well log superimposed on the Full Stack Seismic? If so, this needs to be clarified in the figure”.**
 - This part of the figure caption has now been rephrased to. “The vertical change in the net-to-gross (as seen from the Sand Flag log track) effectively divides the interval into three main lithological zones (b).
 - The well log track shown on the full stack seismic is the P-impedance log. This is now specified as well in the Figure caption “The P-impedance log is superimposed on the full stack seismic section”.

Minor comments

- **Page 1 "within the limmits of the seismic bandwidth. Meanwhile the effective" limmits-> limits**
- **Page 14 "These frequencies where selected based on the dominant" where -> were**
 - ✓ These have now been corrected to “limits” and “were” respectively.

Integrating facies-based Bayesian inversion and supervised machine learning for petrofacies characterisation in the Snadd Formation of the Goliat Field, SW Barents Sea.

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¹ University of Oslo, ² Statoil ASA, ³ Norwegian Geotechnical Institute, ⁴ University of Bergen, ⁵ Eni Norge.
Contact email: hyen@statoil.com

ABSTRACT

Seismic petrofacies characterisation in low net-to-gross reservoirs with poor reservoir properties such as the Snadd Formation in the Goliat field, requires a multidisciplinary approach. This is especially important when the ~~elastic properties of the desired petrofacies significantly overlap~~ desired petrofacies of interest overlap significantly in a rock physics elastic space. Pore fluid corrected end-member sand and shale depth trends have been used to generate stochastic forward models for different lithology and fluid combinations in order to assess the degree of separation of different petrofacies. Subsequently, a spectral decomposition and blending of selected frequency volumes reveal some seismic fluvial geomorphological features. We then jointly inverted for impedance and facies within a Bayesian framework using facies-dependent rock physics depth trends as input. The results from the inversion are then integrated into a supervised machine learning neural network for effective porosity discrimination. Probability density functions derived from stochastic forward modelling of end-member depth trends show a decreasing seismic fluid discrimination with depth. Spectral decomposition and blending of selected frequencies reveal a dominant NNE trend compared to the regional SE – NW progradational trend, and a local E-W trend potentially related to fault activity at branches of the Troms-Finnmark Fault Complex. The facies-based inversion captures the main reservoir facies within the ~~limits~~ limits of the seismic bandwidth. Meanwhile the effective porosity predictions

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9 from the multilayer feedforward neural network are consistent with the inverted facies model, and
10 can be used to qualitatively highlight the cleanest regions within the inverted facies model. A
11 combination of facies-based inversion and neural network improves the seismic reservoir
12 delineation of the Snadd Formation in the Goliat Field.
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19 Keywords: Inversion, rock physics, facies, reservoir characterisation, neural network
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24 INTRODUCTION

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26 The Norwegian Barents Shelf (NBS) is a frontier hydrocarbon exploration province when
27 compared to the other parts of the Norwegian Continental Shelf (NCS) such as North Sea and
28 Norwegian Sea. The NBS has a far more complex burial history, with differential amounts of uplift
29 and erosion within the different basins, platform areas and local highs. Uplift and erosion introduce
30 additional challenges and uncertainties when evaluating the petroleum system with respect to cap
31 rock integrity, source rock maturation, and overconsolidation of the target reservoirs with respect
32 to the present day depths. Understanding and constraining rock physics depth trends is crucial in
33 areas with such a complex burial history.
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41 The Goliat Field is located about 85 km southeast of the Snøhvit gas field (Figure 1) in the
42 Norwegian sector of the Barents Sea. It is the first oil field in the Norwegian sector of the Barents
43 Sea to be in production (March 2016). The majority of the NBS discoveries indicate a dominance
44 of gas over oil. The oil reserves in the Snadd Formation of the Goliat field were not included in
45 the Plan for Development and Operations (PDO). As a result, the Snadd Formation has not been
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9 the focus in earlier studies from a quantitative seismic petrofacies characterisation perspective.
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11 However, a better understanding and delineation of the fluvial sand facies at the top of the Snadd
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13 Formation should provide additional insight into the porosity distribution for the cleanest sand
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15 intervals.

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17 From a geophysical perspective, the Snadd Formation is challenging for the seismic lithology and
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19 fluid characterisation for three main reasons; i) relatively thin, silty-shaly sandstone units not ideal
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21 for AVA (Amplitude Versus Angle) analysis, ii) significant petrofacies overlap in rock physics
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23 elastic properties, and iii) overconsolidated reservoir due to uplift stiffens both the rock frame and
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25 pore space, thereby reducing the seismic fluid sensitivity. The main objective of this study is to
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27 discriminate and map out clean reservoir sands within the Snadd Formation using a
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29 multidisciplinary workflow combining spectral analysis, facies-based Bayesian inversion and
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31 supervised neural networks.
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34 **GEOLOGICAL SETTING**

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36 The Uralian mountain chain is one of the last collision elements close to the study area in Permian-
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38 Triassic times and represents an important source area for the dominantly siliciclastic sediments.
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40 Collapse and erosion of this orogeny, together with sediments from the basement rocks in the Kola
41
42 peninsula, gradually filled the Barents Sea area mainly from the southeast (Mørk 1999; Glørstad-
43
44 Clark et al., 2010; Henriksen et al., 2011b).

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46 Structurally, the Troms-Finnmark Fault Complex (TFFC) is one of several regional faults in the
47
48 area (Figure 1) and it cuts across the Goliat Field. The TFFC has a series of listric normal faults
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50 (Faleide et al., 1984; Gabrielsen, 1984; Gabrielsen et al., 1990; Mulrooney et al., 2017) forming a
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9 prominent roll-over anticline which provides structural closure for the field. Later Cenozoic uplift
10 and exhumation in the Goliat area resulted in approximately 1000 to 1500 m of net erosion (Ohm
11 et al., 2008; Henriksen et al., 2011b; Baig et al., 2016). This implies that the reservoirs have been
12 exposed to much higher pressures and temperatures (i.e., more mechanical and chemical
13 compaction) than at their present depths.
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18 As mentioned earlier, the Snadd Formation is the main focus in this study (Figure 2a). The Barents
19 Sea was part of a large and shallow inland sea, during the time when the Snadd Formation was
20 deposited in the Late Ladinian to Early Norian (Dalland et al., 1988). According to Glørstad-Clark
21 et al. (2010), the main depocenter during this time was located around present day Loppa High.
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26 The regional sequence stratigraphic framework for the Snadd Formations has been documented by
27 several authors (Glørstad-Clark et al., 2010; Klausen et al., 2015). The chronostratigraphic
28 subdivision of the Snadd Formation is based on regionally correlated maximum flooding surfaces
29 (MFS). The Top Snadd Formation sands in the Goliat field are capped by shales of the Fruholmen
30 Formation. It represents the boundary between the Late Triassic Carnian and Norian Stages. This
31 capping shale unit shows a characteristic higher acoustic impedance (AI) than the underlying
32 Snadd Formation sands (Figure 2b). This results to a strong negative reflection coefficient. Note
33 that positive amplitudes represent negative reflection coefficients in Figure 2b due to the reverse
34 polarity of the data. The upper part of the Snadd Formation generally contains thicker and cleaner
35 sands, as opposed to the middle section with more heterolithic or thin interbedded (“ratty”) sands
36 and shales. The base of the Snadd Formation (Ladinian) overlying the Kobbe Formation is
37 dominated by marine shales. This gross vertical change in the sand proportion can easily be seen
38 by looking at the gamma ray log and sand flag (Figure 2b). The Snadd Formation has a southeast
39 to northwest regional depositional dip (Riis et al., 2008; Glørstad-Clark et al., 2010; Klausen et
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10 al., 2015). The boundary between the Snadd Formation and the Kobbe Formation (Anisian to Early
11 Ladinian) below, is characterized by a drop in AI from the basal anoxic shales of the Snadd
12 Formation to the sand prone Kobbe Formation.
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15 The systematic change in the depositional environments for the Snadd Formation, from open
16 marine at the base to non-marine fluvial sediments at the top, translates into ~~an general~~-increase in
17 ~~the~~ net-to-gross (NTG) and quality of the reservoir sands towards the top of the formation. A north
18 – south correlation profile through the available wells is shown in Figure 3a. The wells tops are
19 flattened at the top Snadd Formation pick. Small-scale internal flooding surfaces can be seen
20 bounding a series of stacked fining upward channel sands (blue arrows in the zoomed view in
21 Figure 3a) based on the gamma ray log motif. The NTG at one of the deviated wells (Well-D)
22 shows an anomalous proportion of sand within the Snadd Formation. The same outlier well is
23 located structurally lower in a down – faulted segment compared to the other wells and is bounded
24 by a relay-ramp fault system (Figure 3b).
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36 DATABASE AND METHOD

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38 Long-offset multi-azimuth (MAZ) 3D seismic, wireline logs, prestack depth-migrated (PSDM)
39 velocities, and stratigraphic horizons were provided by the PL229 licence. The MAZ (127°, 67°,
40 and 7°N) 3D seismic data over the Goliat Field each covers an area of approximately 209 km².
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42 During the processing of the seismic data (Buia et al., 2010), the partial angle stacks from the
43 individual azimuths were rotated and referenced to 127°N (consistent with previous older survey
44 azimuth). The near-angle (17°), mid-angle (32°), and far-angle (45°) partial stacks from each
45 rotated azimuth are stacked to provide high quality angle stacks used as input in this study.
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10 The well database consists of seven exploration and appraisal wells. Of these seven wells, two are
11 not drilled through the entire Snadd Formation. Two of the remaining wells (oil- and brine-filled
12 within the Snadd Formation) have been drilled through the entire formation, and in addition
13 contain measured V_s logs. The relevant elastic logs of compressional velocity (V_p), shear velocity
14 (V_s) and bulk density (ρ), alongside a suite of other formation evaluation logs (gamma ray,
15 resistivity, porosity, etc.) have been used for petrofacies characterisation and discrimination during
16 the feasibility analysis. A summary of the data-driven multidisciplinary method used to delineate
17 clean sand units in the Snadd Formation is shown in Figure 4. The ~~full~~ workflow can be subdivided
18 into the following main steps:
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- 25 1. End member depth trend analysis and stochastic forward modelling,
 - 26 2. Rock physics feasibility and facies discrimination
 - 27 3. Well –to – seismic ties and spectral decomposition for seismic geomorphology
 - 28 4. Facies-based Bayesian inversion to predict absolute elastic properties and facies.
 - 29 5. Supervised neural network for porosity estimation
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38 **End-member depth trends and stochastic forward modelling**

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40 A rock physics feasibility analysis ~~generally helps~~ is important in identifying the appropriate
41 quantitative interpretation strategy for the different gross depositional environments within a given
42 basin. This ~~is usually can be~~ done through using crossplots between various well log elastic
43 properties and geological variables like porosity, volume of shale, and water saturation. The degree
44 of facies separation in different elastic domains as a function of depth, provides clues as to which
45 elastic parameters best discriminate the facies of interest. Siliciclastic sediments dominate the
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10 Triassic Snadd Formation. As a result, end member sand and shale facies (Figure 5) have been
11 picked in all the available wells spanning drilled depth. These end-member picks represent the
12 cleanest example of a specific lithofacies. These picks are based on drilling reports, and the full
13 suite of measured and computed petrophysical logs. For the clean sand end-member, the variation
14 in pore fluid properties are also taken into account. The Backus average for each picked zone in
15 the well is used as a single point in the end-member depth trend. During the manual picking
16 process, the relative quality of each end-member pick is assessed from how close the individual
17 pick histogram is to a normal distribution. This ensures that small unusual outliers are not
18 considered and leads to more robust and representative end-member trends.

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26 Once the representative depth trends are obtained for the in situ fluids, Gassmann (1951) fluid
27 substitution is then applied (i.e., referencing all the fluid trends to brine) to effectively remove the
28 scatter in the elastic property depth trends due to variations in the fluid type. The quartz grain and
29 pore fluid properties used for fluid substituting the sand end-member trends are shown in Table 1.
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31 The effective porosity and saturation for each zone pick is obtained from the well logs. The dry
32 rock bulk modulus is inverted for (using Gassmann's equation), given the moduli of quartz and
33 porosity. As a result of a varying porosity input, the inverted dry rock bulk modulus also varies as
34 a function of depth. The final brine-filled, end-member depth-dependent trends can then be used
35 as input to construct i) depth varying stochastic Amplitude Versus Angle (AVA) forward models,
36 ii) depth dependent Gaussian Probability Density Functions (PDFs) of the absolute elastic
37 properties, and iii) the effective Extended Elastic Impedance (EEI) rotation angles (Whitcombe et
38 al., 2002) for lithology and fluid stacks at different depths of investigation.

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47 The stochastic forward models (Figure 6) are based on random sampling from the PDFs at the
48 target depth, between a specified lithology and fluid composite (litho-fluid) across an interface.
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10 This stochastic forward modelling analysis goes beyond the end-member brine trends, but can also
11 include desired or expected litho-fluid composites at different depths. These trends are important
12 in understanding the key elastic parameters controlling the facies discrimination as a function of
13 depth. The depth varying PDFs can later be used to classify the inverted volumes, or other prestack
14 data cross plot combinations (i.e., AVA intercept and gradient, near- versus far-angle stacks), to
15 the desired facies of interest.
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20 These end-member depth trends may be utilised directly in building the very important low-
21 frequency model (LFM) required to obtain absolute elastic properties from a model-based
22 inversion. This requires good prior knowledge of the NTG, which is then used to specify the
23 representative proportions of the end-member trends within each stratigraphic interval. The
24 challenge in doing so is that the NTG distribution within the Snadd Formation is the main objective
25 of the study and the reason for inverting in the first place. As a result, we adopt a different approach
26 to obtain the required low-frequency model, which is explained in the facies-based simultaneous
27 inversion section of the workflow. Prior to the facies-aware inversion, we need to define the target
28 petrofacies from available well data and assign depth dependent rock physics trends.
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36 **Petrofacies classification and per-facies depth trend analysis**

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39 Rock physics crossplots such as AI versus V_p/V_s ratio, colour coded with shale volume and
40 porosity (Figure 7a and Figure 7b respectively), have the potential to reveal facies clusters or trends
41 in petroelastic space. Deciding on the number of petrofacies to invert for is not always trivial.
42 There is a trade-off between the number of different petrofacies needed for subsurface
43 characterisation and the resolution limitations (i.e., narrow bandwidth compared to well log data)
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10 A binary petrofacies log has been created using effective porosity (PHIE) cut-off (PHIE < 12%
11 represent non-reservoir) to distinguish reservoir from non-reservoir. This cut-off is based on how
12 well the derived facies classes separate in the elastic domain. The corresponding AI versus V_p/V_s
13 PDFs of the binary facies are shown in Figure 7b. This binary log was subsequently upscaled based
14 on filtering the PHIE log using a Gaussian function over a 15-m window, and subsequently
15 applying the same cut-off. The upscaled log is used at a later stage for comparison to the inversion-
16 derived facies log at the well locations. Meanwhile, the unscaled facies log is used to define per
17 facies rock physics depth trends. Figure 8a shows the depth trends (using only five vertical wells)
18 for reservoir sand and non-reservoir facies within the Snadd and Kobbe formations interval. Two
19 deviated wells were left out of the depth trend analysis. One of these wells is used as a quality
20 control (QC) blind well for the inversion and neural network predictions. The depth trend analysis
21 provides, i) the prior facies proportions for subsequent facies-based Bayesian inversion, ii)
22 uncertainty distribution (dotted line in Figure 8a) in the elastic properties per facies with depth,
23 and iii), per-facies rock physics cross correlations (Figure 8b) between V_p , V_s , and Rho. The prior
24 probabilities obtained from the depth trends are used as initial estimates only and ~~they usually need~~
25 ~~to be~~ adjusted down slightly to account for bias in well placement (since available wells target
26 areas with expected high NTG). The uncertainty distribution of the elastic properties with depth
27 and the corresponding cross correlations provide important facies-dependent constraints during
28 the Bayesian facies-aware simultaneous inversion process.
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43 **Well-to-seismic ties and spectral analysis**

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45 Well ties represent a crucial step in understanding the relationship between the seismic amplitudes
46 and the impedance contrasts at the wells. This requires a comparison between a synthetic seismic
47 trace and the seismic trace at the well location. The convolutional forward model needed to create
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10 the synthetic trace requires a wavelet. This wavelet can either be derived statistically without using
11 the wells (assuming the seismic data is zero phase), or using a deterministic approach using wells
12 (no assumption of the phase of the data). For this work, we have used the White (1980) method to
13 estimate the wavelets shown in Figure 9a. This deterministic method provides the appropriate
14 wavelet scaler required to link the reflection coefficients computed at the wells to the
15 corresponding observed seismic amplitude. The elastic logs (V_p , V_s , and ρ) are Backus averaged
16 to the seismic bandwidth prior to convolving with the derived wavelet. The quality of the tie is
17 quantitatively assessed using attributes such as the Proportion of Energy Predicted (PEP) and the
18 cross correlation coefficient. The Root Mean Square (RMS) error of the wavelet obtained for each
19 angle stack is used during the inversion to weight the contribution of the near-, mid-, and far-angle
20 stacks differently. The signal-to-noise (SNR) at the target is estimated from the PEP following,

$$SNR = \sqrt{\frac{PEP}{1-PEP}} \quad (1)$$

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32 A spectral decomposition is then carried out on the full stack data. This decomposes the seismic
33 traces to user defined constituent frequencies through a Fourier transform operation within the
34 target window for the Snadd Formation. Analysis of the resulting amplitude spectrum (Figure 9b)
35 and the frequency cube over sand rich intervals around the wells provide insight into which
36 frequencies to select for a Red – Green – Blue (RGB) frequency blend. Seismic geomorphologic
37 features of interest are subsequently highlighted based on an RGB flattened horizon slice for the
38 top Snadd Formation.

39 40 41 42 43 44 45 **Facies-based simultaneous Bayesian inversion**

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10 Seismic data is well known to be bandlimited. However, the low-frequency component of the
11 seismic data is more crucial to the successful application of absolute seismic inversion schemes
12 (Cooke and Schneider, 1983). These low frequencies contain the subtle compaction trends, which,
13 if not properly captured, will result in erroneous estimates of the absolute elastic properties,
14 irrespective of the optimisation inversion algorithm used.
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19 Several practitioners over the years have used different methods to obtain this crucial low-
20 frequency component of the earth. One method is to apply a high-cut frequency to horizon guided
21 interpolations of well log elastic properties. The quality of the LFM is dependent on the number
22 and spacing of the wells. Other methods use seismic velocities (stacking or ~~Prestack-Depth~~
23 ~~Migrated-(PSDM)~~ velocities), either as a standalone input, or co-krigged with the well logs
24 (Yenwongfai et al., 2017a). The seismic Rho and Vs LFMs can be subsequently obtained by
25 applying rock physics transforms such as the Gardner et al. (1974) and Castagna et al. (~~1988~~1998)
26 equations, respectively. The pitfall in using seismic velocities alone is that the corresponding
27 LFMs for Vs and Rho do not contain any independent information. Therefore, in geologic
28 scenarios where the primary facies discriminating parameter is V_p/V_s ratio, the inversion for the
29 purpose of facies discrimination is compromised before one begins. Another method could be to
30 use facies dependent end-member trends as input. The challenge here, as mentioned earlier, is in
31 specifying the correct proportion of the end members, for each zone of interest, to obtain one
32 average LFM. However, it is beyond the scope of this paper to discuss the pitfalls in constructing
33 the LFM or a review of different inversion methods. We refer the reader to Sams and Carter (2017)
34 for more details and alternative methods for constructing a LFM. In addition to the challenges in
35 constructing a LFM, classical inversion algorithms treat the problem as only continuous
36 (impedances), and ignoring facies (discrete) which together drive the seismic response.
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10 In order to overcome these limitations, Kemper and Gunning (2014) introduced a novel approach
11 where the impedances and facies are jointly inverted for in a Bayesian framework. The same
12 method was applied in this study. Here, the LFM is an output (constructed during the inversion)
13 and not an input. Facies-dependent depth trends for V_p , V_s , and ρ are used to construct two LFM
14 representatives for reservoir sand and non-reservoir facies in the Snadd Formation. This ensures
15 that the compaction trends and the associated uncertainty with depth is accounted for per facies.
16 For a detailed review on the inversion scheme, we refer the reader to Kemper and Gunning (2014).
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22 Once facies are obtained, inverse rock physics models per facies (Johansen et al., 2013) can be
23 applied to the inverted facies result to obtain petrophysical parameters like shale volume (V_{sh}),
24 PHIE, and water saturation. For good results, core data calibration is often required. In the absence
25 of available core data, multi-attribute analysis and neural networks were used to combine all
26 available data into one analysis and search for non-linear trends in the data.
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31 **Supervised neural network**

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34 Neural networks have the advantage of exploiting complex non-linear relationships between
35 multiple input parameters to predict a target output. Step-wise linear regression based algorithms
36 might miss some important non-linear information vital for reservoir properties such as PHIE.
37 Utilising neural networks or multi-attribute seismic analysis for lithology characterisation is not
38 new (e.g., Hampson et al., 2001; Pramanik et al., 2004). However, there has been an increasing
39 trend in integrating seismic inversion products with machine learning algorithms to squeeze out
40 more subsurface information.
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47 The main objective of the supervised neural network in this study is to put together in one analysis
48 all relevant attributes derived from the inversion which are indirectly related to the pore volume.
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10 A three-layer feedforward network has been used with a total of 15 nodes in the hidden layer. A
11 sigmoid activation function has been used. The training process is done in time and requires a
12 seismic consistent sampling rate (4 ms in our case) for the target porosity logs (computed from
13 logs measured in depth). Good seismic-to-well ties are crucial during the training phase. First,
14 single attributes are compared and ranked based on their correlation with the PHIE log at the
15 training wells. Then, several multi-attribute combinations are compared and ranked according to
16 the training and validation errors. The optimum number of attributes are chosen based on the
17 validation error profile associated with the successive addition of attributes to the training process.
18 This step tries to reduce the risk of over classifying the attributes in the final neural network. This
19 optimum attribute set is then used as input to the multi-layer feed-forward neural network (MLFN).
20 Optimisation of the cost function is achieved through a combination of conjugate gradient and
21 simultaneous annealing algorithms to search for the global minimum. Meanwhile the optimum
22 synaptic weights between the nodes are derived during the training, by backpropagation of the
23 error in the predicted log when compared to the actual porosity log. The final extracted clean sand
24 geobodies are based on PHIEs > 15 % within the reservoir sand predictions obtained from the
25 facies-based inversion.
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40 RESULTS AND DISCUSSION

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43 Figure 5 shows Gassmann corrected end-member depth trends for sand and shale. All the trends
44 are referenced to brine and plotted from the mudline. The dotted lines represent two standard
45 deviations from the mean trend (solid lines). The black circle on the depth trends represent the
46 approximate top Snadd Formation. As expected, both V_p trends for sand and shale increase as a
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10 function of depth due to increasing mechanical (stress dependent) and chemical (temperature and
11 time dependent) compaction with burial. The porosity loss with increasing burial depth is also
12 captured in the inverse relationship between V_p and PHIE. The end-member trends for P-
13 impedance and Poisson's ratio (ν) become more unique at burial depths greater than that
14 represented by the Snadd Formation. The V_p – Rho relationship is more unique (better end-member
15 separation) than the V_p – V_s trend.
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21 The stochastic forward modelling results for different fluid scenarios using the end-member depth
22 trends as input are shown in Figure 6. The impact of compaction with increasing burial depth on
23 fluid discrimination is illustrated using the Gaussian ellipses and 1D PDFs for AI and V_p/V_s ratio.
24 Gaussian models are compared for brine, oil, and gas-filled sands with a 75% NTG. The centre of
25 each Gaussian ellipse represents the mean for the class. The distance from the mean to the edge of
26 the ellipse is equivalent to two standard deviations. At both modelled depths (1000 m and 2000 m
27 TVD ML), there is a general-significant overlap of the different fluid scenarios. The V_p/V_s ratio
28 shows better discrimination compared to AI at both depth intervals. With increasing burial depth
29 (i.e., at 2000 m TVD ML), we observe that the ellipses for the different fluid scenarios overlap
30 much more. This is as expected because the rock framework becomes stiffer and it is more
31 challenging to determine the pore fluid content. Such an analysis should be done for target
32 reservoirs with contrasting burial depths such as the Snadd Formation, in order to determine the
33 best set of elastic parameters to be used for interpretation at different depths of investigation. For
34 very heterolithic formations with multimodal facies characteristics, the Gaussian assumption
35 might be inadequate and non-parametric multivariate PDFs derived from point density contours in
36 elastic space are more appropriate.
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10 Figure 10 shows the RGB spectral blending flattened top Snadd Formation using iso-frequencies
11 (11, 25, and 55 Hz for Red, Green, and Blue, respectively) decomposed from the full stack data
12 through a Fourier transform operation. These frequencies ~~where-were~~ selected based on the
13 dominant frequency and slope changes in the amplitude spectrum. The dominant frequency from
14 the spectral analysis is ~ 25 Hz. Some large – scale trends can be observed with the hot colours on
15 the map. These bright yellow-red trends are interpreted to represent higher NTG intervals after
16 comparing with the lateral NTG observed at the wells. A strong anomaly around Well-D
17 corresponds with the anomalous sand proportion within the top of the Snadd Formation in the relay
18 ramp area (Figure 3a). Most of the large – scale trends in the northern part of the study area have
19 a NNE orientation (marked with dotted blue lines in Figure 11), except around Well-D with an
20 almost E-W trend. Meanwhile in the southwestern part of the study area the dominant trend
21 changes to ENE. The regional progradation of sediments from the Polar Urals was oriented SE-
22 NW, but some local variations may have occurred around the study area in the Southern
23 Hammerfest Basin (Glørstad-Clark et al., 2010; Klausen et al., 2014). Meanwhile, the E-W trends
24 likely correspond with a locally sourced trend. The branching points along the TFFC (indicated
25 with arrows in Figure 10) show some strong red anomalies with geometries consistent with point-
26 sourced lobes where this major fault branches. The E-W trends and the anomalies tied to the TFFC
27 might be indications of minor local Late Triassic tectonic activity along this master fault
28 (Mulrooney et al., 2017). However, the fidelity of the flattening process is questionable in areas
29 with dense faulting, which limits the resolution of the extracted anomalies, especially when dealing
30 with very thin sands. A closer look into the details in a fault segment with less structuring reveals
31 finer details of what we interpret to be a meandering channel, with a point bar complex. The width
32 of these point bar complexes approximately range between 200 – 250 m. In a low NTG
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10 environment distal from the main source area, it is expected that the channels will develop mud-
11 rich and stable levees, which help in confining the channel and therefore limiting the avulsion
12 frequency. A schematic representation of the meander channel and point bar complex is also shown
13 in Figure 11.
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17 From a qualitative point of view, the seismic-to-well tie within the Snadd Formation is higher at
18 the top and base of the formation. However, it is important to quantitatively assess the fit by
19 examining the PEP and cross correlation over the interval of interest. In the example shown within
20 Track 9 in Figure 12, the PEP is 78 % and the cross correlation is 88 % thus representing a good
21 fit over the target zone.
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26 Figure 11 also shows the comparison between the well logs and the results from both the facies –
27 based Bayesian inversion and the neural network PHIE prediction at the reference well. The well
28 log curves are shown in black, the predicted logs in red, and the blocky red logs within the same
29 track represent the combined facies LFM output. There is a fairly good match between the inverted
30 logs and the actual logs, especially for the thicker sand intervals. In contrast to a model-based
31 deterministic inversion (with the LFM constructed from structurally guided well interpolation),
32 the QC is not compromised because the LFM is not supplied but computed during the inversion.
33 The difference (i.e., residuals) between the inverted traces and the actual seismic trace are also
34 shown in Track 12 in Figure 11 for visual comparison.
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43 The limitations in the seismic bandwidth and the effects of upscaling are more apparent when
44 comparing the derived facies model (Track 7) to the unscaled (Track 5) and upscaled well log
45 facies (Track 6) presented in Figure 11. In this example, there is a good match in the predicted
46 sand units approximately ≥ 15 m. The prior probability for reservoir sand and non-reservoir (Track
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10 8) within the upper part of the Snadd Formation was set as equal. Some smoothing was applied to
11 the prior probabilities (seen as a step pattern on the prior probability curves) to account for
12 gradational facies changes. In addition, the prior probability for reservoir sand is set to decrease
13 towards the base of the Snadd Formation; this is consistent with geologic prior information about
14 the vertical NTG distribution in the available wells. As expected, sand units smaller than 10 m are
15 hardly present in the upscaled facies log and are equally not detected in the inverted facies model.
16 The final facies result is the maximum a posteriori (MAP) facies or most likely facies. In this
17 binary system (reservoir and non-reservoir), this implies a facies probability greater than 50%.
18 However, if more than two facies are being inverted for, it is important to remember that the MAP
19 facies in the Bayesian classification could have a probability as low as 34%.

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28 Figure 12a shows the training (black curve) and validation error (red curve) profiles for a multi-
29 attribute analysis performed to determine the optimum set of attributes to use further in the neural
30 network. Table 2 contains the final list of 10 attribute transforms used. The combined shear
31 Impedance (SI) LFM from the inversion showed the best individual correlation to PHIE. A general
32 well-known problem for neural networks is the potential to over classify the training data set. One
33 way to address this challenge is to start the analysis with a multi-attribute set that results
34 in the smallest validation error (i.e., the lowest turn around point in the validation error profile).
35 The average training error for all wells decreases with successive addition of attributes to the
36 analysis. The lowest minima in the validation error profile occurs at the 10th attribute transform.
37 Each data point on the validation error is obtained leaving out a target well in the analysis and
38 using the other wells to predict the desired property. If more than 10 attributes are used, the
39 prediction quality starts to decrease and we start over classifying the data, i.e., the point at which
40 the average well training error keeps reducing while the validation error progressively increases.
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10 Figure 12b shows a cross plot between the neural network predicted PHIE and actual PHIE log for
11 five wells. The cross correlation between them is 0.67. This plot highlights the underlying
12 challenge in predicting thin, below-resolution clean sand intervals. This challenge is common to
13 the inversion and the neural network result. The prediction does not fully capture the upside in the
14 PHIE estimates. No predicted PHIE data points are observed above 0.2. This is partly due to the
15 sampling rate (4 ms) used in the training which is rather coarse (i.e., for thin high PHIE sand
16 intervals within the Snadd Formation), but consistent to the seismic sampling rate. Track 4 in
17 Figure 11 shows the comparison between the neural network predicted log (red) and the well log
18 (black). The predicted log fully captures the PHIE trend in the log, and is consistent with the
19 inverted facies (Track 7) at the well location.
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28 An arbitrary line (Figure 13) through the reference well and a blind deviated well (i.e., well neither
29 used in the depth trend for the inversion nor in the training for PHIE) validates the inversion and
30 neural network results away from well control. In Figure 13a, the low AI layers ~~generally~~
31 well correlate to reservoir sand facies (Figure 13b) with relatively higher PHIE (Figure 13c) within the upper
32 part of the Snadd Formation. The quality of the facies prediction can be quantified using a
33 confusion matrix. The off-diagonal elements in the matrix indicate the degree of error. The
34 confusion matrices for both wells are displayed in Figure 13b below the corresponding well. For
35 the reference well, the facies aware inversion correctly classifies the reservoir facies of interest
36 87.5 % of the time and wrongly classifies it as non-reservoir 12.5 % of the time. The facies
37 prediction for the deviated blind well, which was not included in defining the facies depth trends,
38 is also shown. The reservoir sand prediction success is 65.38 %. This well has thinner sand units
39 compared to the reference well, and this could be one reason for a lower classification success. In
40 reservoirs where the facies do not show separate clusters in a rock physics space, the wavelet
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10 scaling becomes more crucial to the inversion result. However, the White (1980) method provided
11 the appropriate wavelet scaling required in our case. Notice that the middle to lower section of the
12 Snadd Formation (Figure 13c) is dominated by PHIEs < 0.1 and is correctly classified as non-
13 reservoir (Figure 13b) in the facies-based inversion. Despite the upside limitation in the predicted
14 PHIE result, it is still very useful in a qualitative sense when combined with the inverted facies, to
15 highlight the cleanest intervals within the predicted reservoir sands in the upper parts of the Snadd
16 Formation.
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22 Figure 14 shows a horizon slice for PHIE and facies at the top of the Snadd Formation interval.
23 The ovals and arrows from the RGB flattened slice in Figure 10 are shown for a visual qualitative
24 comparison between the attributes. The extent of the anomalies indicating gross depositional trends
25 (Figure 10) are much larger than observed in the PHIE (Figure 14a) and Facies (Figure 14b)
26 horizon slices. In general, there is consistency between the PHIE and Facies horizon slices with a
27 few exceptions. The large white ovals in Figure 14 show areas with predicted reservoir sand but
28 with very low porosity predictions. This could be interpreted to represent more cemented sands,
29 as this area structurally lower (easily seen in Figure 3b around the grey arrow) within a graben
30 structure bounded by relay ramp faults. The combined map (Figure 14c) showing the clean sand
31 geobodies represent predicted sand facies with PHIEs $> 15\%$. Artefacts are produced along the
32 faults in both the facies and PHIE maps and reliability of the maps increase away from the faults.
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44 CONCLUSION

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47 Properly constrained facies-dependent rock physics depth trends are very important for successful
48 quantitative seismic reservoir characterisation within the Snadd Formation in the Goliat field.
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10 However, if these trends are to be used in other parts of the SW Barents Shelf, an appropriate
11 reference depth needs to be thoroughly investigated before hanging the depth trends in areas with
12 seismic data but no wells. Fluid sensitivity is shown to decrease with depth based on the PDFs
13 obtained from the end member trends. Spectral decomposition and RGB blended results reveal
14 two main depositional trends: i) a NNE trend compared to the SE – NW regional clinoform
15 progradation of sediments from the Uralide orogeny, and ii) an E-W local trend which likely
16 represents local sources tied to pulses of sediments at branching points of the TFFC. The Snadd
17 Formation is strongly compartmentalised so the fidelity of the flattened slice is uncertain in
18 intensively faulted areas.
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26 Despite the considerable overlap of the binary facies in a rock physics elastic space, the facies-
27 aware Bayesian inversion is still able to largely discriminate reservoir sands from non-reservoir at
28 a blind well (i.e., not used in the depth trend analysis). When inverting for more than two facies,
29 it is crucial to further investigate the probability of the most likely facies which can be as low as
30 26% (i.e., if four facies are inverted for).
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35 The neural network porosity predictions capture the general vertical trends in the wells, but do not
36 properly capture the very thin high PHIE sands. However, the PHIE results are consistent with the
37 inverted facies and can be used in a qualitative manner to discriminate the best reservoir facies
38 with high PHIE. Areas interpreted to represent point sources for sediment input along the TFFC
39 from the RGB flattened slice are supported by both facies and PHIE predictions. Neural networks
40 should be viewed as an additional tool to decode complex relationships in the data especially when
41 available linear and non-linear rock physics models fail.
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LIST OF FIGURES

Figure 1 Location map for the Goliat Field (adapted from NPD factmaps) in the Norwegian sector of the Barents Sea. The field is cut by the Troms–Finnmark Fault Complex within blocks 7122/7 and 7122/8 (Yenwongfai et al., 2017a)

Figure 2 Triassic chronostratigraphic framework comparison (a) for different authors. The subdivisions are based on 2nd and 3rd order sequences (Klausen et al., 2015). The Snadd Formation (target in this study) is also starred. The vertical change in the net-to-gross (as seen from the Sand Flag log track) effectively divides the interval into three main lithological zones (b). ~~Notice the vertical change in the net-to-gross effectively dividing the interval into three main lithological zones (b).~~ Zone 1 has thicker more consistent sand units. Meanwhile zone 2 and 3 have heterolithic sands and shales respectively. ~~Maximum flooding surfaces (MFSs) bounding the top and base of the Snadd Formation are also indicated.~~ The P-impedance log is superimposed on the full stack seismic section. Note that positive amplitudes on the seismic represent soft events.

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10 **Figure 3** Well correlation profile from north to south. Well-D has an anomalous high sand
11 proportion within the Snadd Formation and is located within a relay ramp structure (black arrow).
12 Well-D is a side track from Well-G (not visible in Figure 3b) and deviates further away from Well-
13 G below the top Snadd Formation horizon. Minor faults around both wells might explain
14 differences in the observed NTG. Gamma log motifs from Well-B show good examples of stacked
15 fining upward channels bounded by flooding surfaces.
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20 **Figure 4** ~~Summary w~~Workflow implemented for petrofacies and PHIE characterisation within the
21 Snadd Formation. Depth trends play a central role in the feasibility study and during the inversion.
22 The flow diagram shows the routes to ~~seismic facies characterisation-clean sand delineation. The~~
23 five main steps in the seismic reservoir characterisation workflow are highlighted in green.
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28 **Figure 5:** End-member depth trends for sand and shale through the whole well interval. The V_p ,
29 V_s , ρ , and PHIE trends are the primary trends (a) while the other trends (b) are derived from
30 the primary trends. The sand-end member trends have been Gassmann fluid substituted to brine.
31 The black circle shows the approximate depth location of the top Snadd Formation.
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36 **Figure 6:** Depth varying PDFs (a) based on stochastic forward modelling of the end-member
37 trends (shown in Figure 5). The plots show the fluid discrimination of AI and V_p/V_s attributes as
38 a function of depth. Sensitivity decreases with depth as shown by increasing overlap of each ellipse
39 and PDFs. Also the effective extended elastic impedance (EEI) chi angle (c) using the depth trends
40 are also shown. The black and red arrows indicate the effective lithology and fluid angles.
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45 **Figure 7** AI versus V_p/V_s cross plots colour coded with Vsh (a) and PHIE (b). The contour density
46 for sand and shale are based on a PHIE cut-off using 12% as the threshold. Sands dominate at low
47 AI and V_p/V_s ratios. However, the histograms still show a significant overlap of both facies.
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10 **Figure 8** Reservoir and non-reservoir depth trends within the Snadd and kobbe Formation time
11 interval. These depth trends (a) provide the uncertainty distribution (standard deviation of the
12 derived trend curve) of the elastic properties as a function of depth as well as the cross correlation
13 and constraints between the elastic parameters per facies. A cross plot comparison (b) between the
14 prior model derived from the depth trends and the corresponding well data are also shown.
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19 **Figure 9** Wavelet processing and spectral analysis. The near, mid, and far angle stack wavelets (a)
20 have all been extracted using the White (1980) method. The wavelets have been extracted based
21 on the offset location with the highest PEP close to the well bore. The signal and noise spectra (b)
22 at the top of the Snadd Formation interval are also shown with the selected frequencies used in the
23 RGB blend.
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28 **Figure 10:** Spectral decomposition and RGB blending of selected frequencies displayed at the top
29 Snadd Formation flattened horizon slice. The corresponding frequency spectra (Figure 9b) is also
30 inserted for reference to the frequencies. The bright red arrows show a dominant NNE trend.
31 Meanwhile close to the branching points along the Troms-Finnmark Fault Complex (TFFC),
32 observed anomalies are oriented E – W (black dotted lines). The white dotted lines, show the
33 anomaly around Well-D (anomalous sand proportion in Figure 3) indicated with a blue arrow. A
34 detailed view around Well-E shows a schematic representation of a channel and point bar complex.
35 Note that Well-E just sits at the edge of this anomaly.
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43 **Figure 11:** Facies-aware inversion and neural network results at the reference well. The inverted
44 elastic logs (blue logs in Track 2 and 3) are plotted alongside the LFM (low frequency model)
45 output logs (red logs) in the same tracks. There is a good match between the inverted facies log
46 (Track 7) compared to the upscaled (Track 6). The inversion synthetic logs and the residuals are
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10 also shown in Track 11 and Track 12. The predicted PHIE log (red) from the neural network shows
11 a match to the thicker and better developed reservoir sands (above 1240 ms TWT).
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13 **Figure 12** Multi-attribute neural network training (a) and prediction correlation (b). The validation
14 error is shown to increase after the 10th attribute transform in the multi-attribute analysis. Attribute
15 number 1 – 10 are used in the neural network prediction. We refer the reader to Table 2 for more
16 details in Figure 12a.
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21 **Figure 13** Arbitrary line section through the reference well (Well-A) and the blind well (Well-C).
22 The simultaneous Bayesian Joint Impedance (a) and Facies (b) inversion results are compared with
23 the neural network PHIE predictions (c). Good PHIEs observed at the upper part of the Snadd
24 Formation (results from the neural network) are consistent with the predicted reservoir sands from
25 the inversion. The quality of the facies predictions are illustrated in a confusions matrix below the
26 respective wells. Diagonal elements in the matrix indicate the degree of success of the
27 classification.
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34 **Figure 14** Horizon slices at the top of the Snadd Formation for effective porosity (a) and binary
35 facies (b) over a 30ms window. The binary facies map is the result from the facies-based inversion,
36 while the the porosity map is the output from the multi-layer feedforward neural network. The
37 clean sand geobodies (c) represent predicted reservoir sand facies with PHIE greater than 15 %.
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41 Reservoir delineation is improved by qualitatively combining areas with good effective porosity
42 in regions where reservoir sand is predicted by the inversion. The arrows and ovals from the
43 flattened RGB slice in Figure 10, are inserted for visual comparison.
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12 **LIST OF TABLES**
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14 **Table 1:** Grain and fluid properties used as input for brine substitution of the sand end-member
15 trend through Gassmann's equation. Quartz properties have been used for sand end-member
16 grain properties.
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20 **Table 2:** Multi-attribute transform list used as input to the neural network. Attribute numbers
21 correspond to numbers used in Figure 13a. The attribute transform with the highest individual
22 correlation to PHIE, is the Shear Impedance (SI) LFM output constructed during the inversion.
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24 Note that the errors associated with each successive is attribute is cumulative by applying all
25 preceding attributes.
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